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Eigenvalues and eigenvectors of tau matrices with applications to Markov processes and economics

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ABSTRACT

In the context of matrix displacement decomposition, Bozzo and Di Fiore introduced the so-called $\tau_{\varepsilon,\varphi}$ algebra, a generalization of the well known τ algebra. We study the properties of eigenvalues and eigenvectors of the generator $T_{n,\varepsilon,\varphi}$ of the $\tau_{\varepsilon,\varphi}$ algebra. In particular, we derive the asymptotics for the outliers of $T_{n,\varepsilon,\varphi}$ and the associated eigenvectors; we obtain equations for the eigenvalues of $T_{n,\varepsilon,\varphi}$, which provide also the eigenvectors of $T_{n,\varepsilon,\varphi}$; and we compute the full eigendecomposition of $T_{n,\varepsilon,\varphi}$ in the specific case $\varepsilon\varphi = 1$. We also present applications of our results in the context of queuing models, random walks, and diffusion processes, with a special attention to their implications in the study of wealth/income inequality and portfolio dynamics.

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1. Introduction

Consider the $n \times n$ matrix

$$T_{n,\varepsilon,\varphi} = \begin{bmatrix} \varepsilon & 1 & & & \\ 1 & 0 & 1 & & \\ & \ddots & \ddots & \ddots & \\ & & 1 & 0 & 1 \\ & & & 1 & \varphi \end{bmatrix},$$

where $\varepsilon, \varphi \in \mathbb{R}$ are given parameters. For $\varepsilon, \varphi \in \{0, 1, -1\}$, the eigendecomposition of $T_{n,\varepsilon,\varphi}$ is already available in the literature. In particular, for $(\varepsilon, \varphi) = (0, 0)$, the matrix $T_{n,\varepsilon,\varphi} = T_{n,0,0}$ is the generator of the τ algebra; its eigendecomposition, as well as the eigendecomposition of any tridiagonal Toeplitz matrix, has long been known [9, Section 2.2]. For $(\varepsilon, \varphi) \neq (0, 0)$, the matrix $T_{n,\varepsilon,\varphi}$ is the generator of the so-called $\tau_{\varepsilon,\varphi}$ algebra introduced by Bozzo and Di Fiore in [10]; its eigendecomposition for $(\varepsilon, \varphi) = (1, 1), (-1, -1), (1, -1), (-1, 1)$ was provided in [10, Section 4]. Finally, for $(\varepsilon, \varphi) = (1, 0), (0, 1), (-1, 0), (0, -1)$ —actually for all $\varepsilon, \varphi \in \{0, 1, -1\}$ —the eigendecomposition of $T_{n,\varepsilon,\varphi}$ was obtained by Losonczi [26, Section 3] along with the eigendecomposition of more general tridiagonal matrices. We refer the reader to [12, Appendix 1, pp. 394–395] for a different approach with respect to Losonczi's, to the recent survey [15] for a due tribute to Losonczi's pioneering work [26], and to [13,14,16] for further studies on the eigenvalues and eigenvectors of special structured tridiagonal matrices.

For all $\varepsilon, \varphi \in \mathbb{R}$, the asymptotic spectral distribution of $T_{n,\varepsilon,\varphi}$ in Weyl's sense can be easily obtained from the theory of generalized locally Toeplitz sequences [20,21], which immediately yields for $T_{n,\varepsilon,\varphi}$ the asymptotic spectral distribution function $2 \cos \theta$. Precise eigenvalue estimates can also be given on the basis of classical interlacing results [23, Section 4.3] after observing that $T_{n,\varepsilon,\varphi}$ is a small-rank perturbation of $T_{n,0,0}$ and the eigenvalues of $T_{n,0,0}$ are known. It should be noted, however, that both asymptotic spectral distribution results and interlacing estimates completely ignore the outliers of $T_{n,\varepsilon,\varphi}$, i.e., the eigenvalues lying outside the interval $[-2, 2]$ (the range of $2 \cos \theta$). On the other hand, the outliers, which are determined by the parameters ε, φ , are precisely the objects one is interested in when dealing with several noteworthy applications. Such applications include, for example, queuing models and Markov chains/processes [3,7,22,25], where the eigenvector corresponding to the (unique) outlier of (a suitable transform of) $T_{n,\varepsilon,\varphi}$ corresponds to the steady-state distribution of the considered chain/process.

In this paper, we study the spectral properties of $T_{n,\varepsilon,\varphi}$ and present a few applications in the context of Markov chains/processes, with a special focus on queuing models,

random walks, diffusion processes and economics issues. The structure of the paper, including a summary of our contributions, is given below.

- In Section 2, we study some basic spectral properties of $T_{n,\varepsilon,\varphi}$ that will simplify the analysis of later sections.
- In Section 3, we derive the asymptotics of the outliers of $T_{n,\varepsilon,\varphi}$ and the associated eigenvectors. Our main results in this regard are Theorems 3.1–3.3, which are illustrated through numerical experiments in Tables 3.1–3.3.
- In Section 4, we derive equations for the eigenvalues of $T_{n,\varepsilon,\varphi}$. For all $\varepsilon, \varphi \in \mathbb{R}$ for which these equations can be solved, one obtains not only the eigenvalues but also the eigenvectors of $T_{n,\varepsilon,\varphi}$. Our main results in Section 4 are Theorems 4.1–4.5. It should be noted, however, that such results cannot be considered as an original contribution of this paper, because they have already been obtained by Losonczy [26], though with a different approach and without a focus on the outliers as in Theorems 4.2 and 4.4.
- In Section 5, we solve the equations obtained in Section 4 for specific values of ε, φ . In particular, we show how it is possible to re-obtain through these equations the eigendecomposition of $T_{n,\varepsilon,\varphi}$ for $\varepsilon, \varphi \in \{0, 1, -1\}$; and we address the new case $\varepsilon\varphi = 1$, which is the case of interest for the applications presented in Section 6.
- In Section 6, we present a few applications in the context of Markov chains/processes, with a special focus on queuing models, random walks in a multidimensional lattice, multidimensional reflected diffusion processes and economics issues. In particular, we investigate the implications of our results within a model for wealth/income inequality and portfolio dynamics with an arbitrary number of assets: we provide analytical formulas for the steady-state (stationary) distribution of the underlying stochastic process (a multidimensional reflected diffusion process), we compute the convergence speed to the steady state, and we also derive closed-form expressions for relevant moments of the stationary distribution such as the average wealth and the wealth variance.
- In Section 7, we draw conclusions and outline possible future lines of research.

2. Basic properties of the eigenvalues and eigenvectors of $T_{n,\varepsilon,\varphi}$

In this section, we collect some basic properties of the eigenvalues and eigenvectors of $T_{n,\varepsilon,\varphi}$ which will allow us to tackle the analysis of the next sections with useful a priori knowledge. Throughout this paper, the eigenvalues of $T_{n,\varepsilon,\varphi}$ which do not belong to $[-2, 2]$ are referred to as outliers. We denote by $\mathbf{e}_1, \dots, \mathbf{e}_n$ the vectors of the canonical basis of \mathbb{R}^n , and by E_n the exchange matrix whose rows are those of the identity matrix I_n in reverse order:

$$E_n = \begin{bmatrix} & & & & 1 \\ & & & & \\ & & & & \\ & & & & \\ 1 & & & & \end{bmatrix}.$$

Proposition 2.1. *The following properties hold.*

1. $T_{n,\varphi,\varepsilon} = E_n T_{n,\varepsilon,\varphi} E_n$. Hence, (λ, \mathbf{u}) is an eigenpair of $T_{n,\varepsilon,\varphi}$ if and only if $(\lambda, E_n \mathbf{u})$ is an eigenpair of $T_{n,\varphi,\varepsilon}$.
2. If $\varepsilon \neq 0$ and

$$\mathbf{v}_n = [\varepsilon^{-i+1}]_{i=1}^n = [1, \varepsilon^{-1}, \dots, \varepsilon^{-n+1}]^\top,$$

then $T_{n,\varepsilon,\varphi} \mathbf{v}_n - (\varepsilon + \varepsilon^{-1}) \mathbf{v}_n = \varepsilon^{-n} (\varepsilon \varphi - 1) \mathbf{e}_n$. Similarly, if $\varphi \neq 0$ and

$$\mathbf{w}_n = [\varphi^{-n+i}]_{i=1}^n = [\varphi^{-n+1}, \dots, \varphi^{-1}, 1]^\top,$$

then $T_{n,\varepsilon,\varphi} \mathbf{w}_n - (\varphi + \varphi^{-1}) \mathbf{w}_n = \varphi^{-n} (\varepsilon \varphi - 1) \mathbf{e}_1$.

3. $T_{n,\varepsilon,\varphi}$ has n real distinct eigenvalues.
4. If $|\varepsilon|, |\varphi| \leq 1$, then all the eigenvalues of $T_{n,\varepsilon,\varphi}$ belong to $[-2, 2]$.
5. If $|\varepsilon| \leq 1, |\varphi| > 1$ or $|\varepsilon| > 1, |\varphi| \leq 1$, then all the eigenvalues of $T_{n,\varepsilon,\varphi}$ belong to $[-2, 2]$ except for at most 1 outlier.
6. If $|\varepsilon|, |\varphi| > 1$, then all the eigenvalues of $T_{n,\varepsilon,\varphi}$ belong to $[-2, 2]$ except for at most 2 outliers.
7. If $|\varepsilon| < 1$ or $|\varphi| < 1$, then both 2 and -2 are not eigenvalues of $T_{n,\varepsilon,\varphi}$.

Proof. 1. It follows from direct computation.

2. It follows from direct computation.

3. $T_{n,\varepsilon,\varphi}$ is nonderogatory just like any Hessenberg matrix with nonzero subdiagonal entries [23, p. 82]. Since $T_{n,\varepsilon,\varphi}$ is also real and symmetric (hence diagonalizable), we infer that $T_{n,\varepsilon,\varphi}$ has n real distinct eigenvalues.

4. The result follows immediately from Gershgorin’s theorem [23, Theorem 6.1.1].

5. We prove the statement in the case where $|\varepsilon| \leq 1$ and $|\varphi| > 1$ (the proof in the other case is identical). Write

$$T_{n,\varepsilon,\varphi} = T_{n,\varepsilon,0} + \varphi \mathbf{e}_n \mathbf{e}_n^\top.$$

All the eigenvalues of $T_{n,\varepsilon,0}$ belong to $[-2, 2]$ by Gershgorin’s theorem. Since the unique nonzero eigenvalue of the matrix $\varphi \mathbf{e}_n \mathbf{e}_n^\top$ is φ , it follows from a classical interlacing theorem [23, Corollary 4.3.3] that $n - 1$ eigenvalues of $T_{n,\varepsilon,\varphi}$ belong to $[-2, 2]$.

6. Write

$$T_{n,\varepsilon,\varphi} = T_{n,0,0} + \varepsilon \mathbf{e}_1 \mathbf{e}_1^\top + \varphi \mathbf{e}_n \mathbf{e}_n^\top.$$

All the eigenvalues of $T_{n,0,0}$ belong to $[-2, 2]$ by Gershgorin’s theorem. Since the unique nonzero eigenvalues of the matrix $\varepsilon \mathbf{e}_1 \mathbf{e}_1^\top + \varphi \mathbf{e}_n \mathbf{e}_n^\top$ are ε and φ , it follows from [23, Corollary 4.3.3] that $n - 2$ eigenvalues of $T_{n,\varepsilon,\varphi}$ belong to $[-2, 2]$.

7. The result follows immediately from the fact that the matrix $T_{n,\varepsilon,\varphi}$ is irreducible and from the so-called Gershgorin’s third theorem [8, p. 80]. \square

3. Asymptotics of the outliers of $T_{n,\varepsilon,\varphi}$

If $|\varepsilon| > 1$ and n is large enough, Property 2 of Proposition 2.1 says that $(\varepsilon + \varepsilon^{-1}, \mathbf{v}_n)$ is substantially an eigenpair of $T_{n,\varepsilon,\varphi}$ (it is an exact eigenpair if $\varepsilon\varphi = 1$). A similar consideration applies to $(\varphi + \varphi^{-1}, \mathbf{w}_n)$. The next theorems formalize this intuition. We remark that, for every $x > 0$,

$$x + x^{-1} = 2 \cosh(\log x) \geq 2,$$

with equality holding if and only if $x = 1$. In what follows, $\sigma(X)$ denotes the spectrum of the matrix X .

Lemma 3.1. *The following properties hold.*

1. If $|\varepsilon| > 1$, then there exists an eigenvalue μ_n of $T_{n,\varepsilon,\varphi}$ such that $\mu_n \rightarrow \varepsilon + \varepsilon^{-1}$ as $n \rightarrow \infty$. Since $|\varepsilon + \varepsilon^{-1}| > 2$, the eigenvalue μ_n is eventually an outlier.
2. If $|\varphi| > 1$, then there exists an eigenvalue ν_n of $T_{n,\varepsilon,\varphi}$ such that $\nu_n \rightarrow \varphi + \varphi^{-1}$ as $n \rightarrow \infty$. Since $|\varphi + \varphi^{-1}| > 2$, the eigenvalue ν_n is eventually an outlier.

Proof. 1. Let $\{\mathbf{u}_{1,n}, \dots, \mathbf{u}_{n,n}\}$ be an orthonormal basis of \mathbb{R}^n formed by eigenvectors of $T_{n,\varepsilon,\varphi}$ with corresponding eigenvalues $\lambda_{1,n}, \dots, \lambda_{n,n}$:

$$T_{n,\varepsilon,\varphi} \mathbf{u}_{i,n} = \lambda_{i,n} \mathbf{u}_{i,n}, \quad i = 1, \dots, n.$$

Expand the vector $\mathbf{v}_n = [1, \varepsilon^{-1}, \dots, \varepsilon^{-n+1}]^\top$ on this basis:

$$\mathbf{v}_n = \sum_{i=1}^n \alpha_{i,n} \mathbf{u}_{i,n}, \tag{3.1}$$

$$\sum_{i=1}^n \alpha_{i,n}^2 = \|\mathbf{v}_n\|_2^2 = \frac{1 - \varepsilon^{-2n}}{1 - \varepsilon^{-2}} \rightarrow \frac{1}{1 - \varepsilon^{-2}}. \tag{3.2}$$

The equation $T_{n,\varepsilon,\varphi} \mathbf{v}_n - (\varepsilon + \varepsilon^{-1}) \mathbf{v}_n = \varepsilon^{-n}(\varepsilon\varphi - 1) \mathbf{e}_n$ in Proposition 2.1 becomes

$$\sum_{i=1}^n (\lambda_{i,n} - (\varepsilon + \varepsilon^{-1})) \alpha_{i,n} \mathbf{u}_{i,n} = \varepsilon^{-n}(\varepsilon\varphi - 1) \mathbf{e}_n. \tag{3.3}$$

Passing to the norms, we obtain

$$\sum_{i=1}^n (\lambda_{i,n} - (\varepsilon + \varepsilon^{-1}))^2 \alpha_{i,n}^2 = \varepsilon^{-2n}(\varepsilon\varphi - 1)^2 \rightarrow 0. \tag{3.4}$$

If we assume by contradiction that $\text{dist}(\sigma(T_{n,\varepsilon,\varphi}), \varepsilon + \varepsilon^{-1}) = \min_{i=1, \dots, n} |\lambda_{i,n} - (\varepsilon + \varepsilon^{-1})| \not\rightarrow 0$ as $n \rightarrow \infty$, then there exists a positive constant c such that

Table 3.1

Illustration of Theorem 3.1 in the case $\varepsilon = 3$ and $\varphi = 1/2$ where $\varepsilon + \varepsilon^{-1} = 3.\bar{3}$. For every n we have denoted by μ_n the unique outlier of $T_{n,\varepsilon,\varphi}$ and by \mathbf{x}_n the corresponding normalized eigenvector computed by JULIA.

n	outlier μ_n	$ \mu_n - (\varepsilon + \varepsilon^{-1}) $	$\ \mathbf{x}_n - P_{\mathbf{v}_n} \mathbf{x}_n\ _2$
8	3.3333333663723654	$3.3 \cdot 10^{-8}$	$3.0 \cdot 10^{-5}$
16	3.3333333333333341	$7.7 \cdot 10^{-16}$	$4.6 \cdot 10^{-9}$
32	3.3333333333333333	$4.1 \cdot 10^{-31}$	$1.1 \cdot 10^{-16}$
64	3.3333333333333333	$1.2 \cdot 10^{-61}$	$5.8 \cdot 10^{-32}$
128	3.3333333333333333	$1.0 \cdot 10^{-122}$	$1.7 \cdot 10^{-62}$

$$\text{dist}(\sigma(T_{n,\varepsilon,\varphi}), \varepsilon + \varepsilon^{-1}) \geq c$$

frequently as $n \rightarrow \infty$, hence

$$\sum_{i=1}^n (\lambda_{i,n} - (\varepsilon + \varepsilon^{-1}))^2 \alpha_{i,n}^2 \geq c^2 \sum_{i=1}^n \alpha_{i,n}^2 = c^2 \|\mathbf{v}_n\|_2^2 \geq c^2$$

frequently as $n \rightarrow \infty$, which is a contradiction to (3.4). We conclude that $\text{dist}(\sigma(T_{n,\varepsilon,\varphi}), \varepsilon + \varepsilon^{-1}) \rightarrow 0$ as $n \rightarrow \infty$, which is the thesis.

2. It follows from item 1 applied to $T_{n,\varphi,\varepsilon}$, taking into account that $\sigma(T_{n,\varphi,\varepsilon}) = \sigma(T_{n,\varepsilon,\varphi})$ by Proposition 2.1. \square

If $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$, we set $(\mathbf{x}, \mathbf{y}) = \mathbf{x}^\top \mathbf{y}$. If $\mathbf{u} \in \mathbb{R}^n$, we denote by $P_{\mathbf{u}}$ the orthogonal projector onto the subspace $\langle \mathbf{u} \rangle$ generated by \mathbf{u} . In the case where $\mathbf{u} \neq \mathbf{0}$, the projector $P_{\mathbf{u}}$ is explicitly given by

$$P_{\mathbf{u}} \mathbf{x} = \frac{(\mathbf{x}, \mathbf{u})}{(\mathbf{u}, \mathbf{u})} \mathbf{u}, \quad \mathbf{x} \in \mathbb{R}^n.$$

Theorem 3.1. *Suppose that $|\varepsilon| > 1$ and $\varphi \neq \varepsilon$. Let (μ_n, \mathbf{x}_n) be an eigenpair of $T_{n,\varepsilon,\varphi}$ such that $\mu_n \rightarrow \varepsilon + \varepsilon^{-1}$ as $n \rightarrow \infty$ and $\|\mathbf{x}_n\|_2 = 1$ for all n . Then, the following properties hold.*

1. *Eventually, μ_n is an outlier of $T_{n,\varepsilon,\varphi}$ and any other eigenvalue $\lambda_n \in \sigma(T_{n,\varepsilon,\varphi})$ satisfies $|\lambda_n - (\varepsilon + \varepsilon^{-1})| \geq c$ for some positive constant c independent of n .*
2. *$\|\mathbf{x}_n - P_{\mathbf{v}_n} \mathbf{x}_n\|_2 \rightarrow 0$ as $n \rightarrow \infty$, where $\mathbf{v}_n = [1, \varepsilon^{-1}, \dots, \varepsilon^{-n+1}]^\top$.*

Proof. 1. If $|\varphi| \leq 1$, then all eigenvalues of $T_{n,\varepsilon,\varphi}$ belong to $[-2, 2]$ except for at most 1 outlier (by Proposition 2.1). Since $\mu_n \rightarrow \varepsilon + \varepsilon^{-1} \notin [-2, 2]$, it is clear that μ_n coincides eventually with the unique outlier of $T_{n,\varepsilon,\varphi}$. Moreover, any other eigenvalue λ_n of $T_{n,\varepsilon,\varphi}$ satisfies the inequality $|\lambda_n - (\varepsilon + \varepsilon^{-1})| \geq c$ with

$$c = \text{dist}(\varepsilon + \varepsilon^{-1}, [-2, 2]).$$

If $|\varphi| > 1$, then all eigenvalues of $T_{n,\varepsilon,\varphi}$ belong to $[-2, 2]$ except for at most 2 outliers (by Proposition 2.1) and there exists an eigenvalue ν_n of $T_{n,\varepsilon,\varphi}$ such that $\nu_n \rightarrow \varphi + \varphi^{-1} \notin [-2, 2]$ (by Lemma 3.1). Since $\mu_n \rightarrow \varepsilon + \varepsilon^{-1} \notin [-2, 2]$ and $\varepsilon + \varepsilon^{-1} \neq \varphi + \varphi^{-1}$ (because $\varphi \neq \varepsilon$ by assumption), it is clear that, eventually, $\mu_n \neq \nu_n$ and μ_n, ν_n are the unique two outliers of $T_{n,\varepsilon,\varphi}$. Moreover, any eigenvalue λ_n of $T_{n,\varepsilon,\varphi}$ with $\lambda_n \neq \mu_n$ satisfies eventually the inequality $|\lambda_n - (\varepsilon + \varepsilon^{-1})| \geq c$ with

$$c = \text{dist}(\varepsilon + \varepsilon^{-1}, [-2, 2] \cup [\varphi + \varphi^{-1} - \delta, \varphi + \varphi^{-1} + \delta]),$$

where δ is a fixed positive constant chosen so that $\varepsilon + \varepsilon^{-1} \notin [\varphi + \varphi^{-1} - \delta, \varphi + \varphi^{-1} + \delta]$.

2. Let $\{\mathbf{u}_{1,n}, \dots, \mathbf{u}_{n,n} = \mathbf{x}_n\}$ be an orthonormal basis of \mathbb{R}^n formed by eigenvectors of $T_{n,\varepsilon,\varphi}$ with corresponding eigenvalues $\lambda_{1,n}, \dots, \lambda_{n,n} = \mu_n$:

$$T_{n,\varepsilon,\varphi} \mathbf{u}_{i,n} = \lambda_{i,n} \mathbf{u}_{i,n}, \quad i = 1, \dots, n.$$

We expand the vector \mathbf{v}_n on this basis as in (3.1) and we get (3.2)–(3.4). By item 1, we eventually have

$$\sum_{i=1}^n (\lambda_{i,n} - (\varepsilon + \varepsilon^{-1}))^2 \alpha_{i,n}^2 \geq c^2 \sum_{i=1}^{n-1} \alpha_{i,n}^2 + (\mu_n - (\varepsilon + \varepsilon^{-1}))^2 \alpha_{n,n}^2. \tag{3.5}$$

Hence, by (3.2) and (3.4),

$$\sum_{i=1}^{n-1} \alpha_{i,n}^2 \rightarrow 0, \quad \alpha_{n,n}^2 \rightarrow \frac{1}{1 - \varepsilon^{-2}}. \tag{3.6}$$

Keeping in mind (3.1), (3.2) and (3.6), we obtain

$$\begin{aligned} \|\mathbf{x}_n - P_{\mathbf{v}_n} \mathbf{x}_n\|_2^2 &= \|\mathbf{u}_{n,n} - P_{\mathbf{v}_n} \mathbf{u}_{n,n}\|_2^2 = \left\| \mathbf{u}_{n,n} - \frac{(\mathbf{u}_{n,n}, \mathbf{v}_n)}{(\mathbf{v}_n, \mathbf{v}_n)} \mathbf{v}_n \right\|_2^2 \\ &= \left\| \mathbf{u}_{n,n} - \frac{\alpha_{n,n}}{\|\mathbf{v}_n\|_2^2} \sum_{i=1}^n \alpha_{i,n} \mathbf{u}_{i,n} \right\|_2^2 \\ &= \left\| \left(1 - \frac{\alpha_{n,n}^2}{\|\mathbf{v}_n\|_2^2}\right) \mathbf{u}_{n,n} + \frac{\alpha_{n,n}}{\|\mathbf{v}_n\|_2^2} \sum_{i=1}^{n-1} \alpha_{i,n} \mathbf{u}_{i,n} \right\|_2^2 \\ &= \left(1 - \frac{\alpha_{n,n}^2}{\|\mathbf{v}_n\|_2^2}\right)^2 + \frac{\alpha_{n,n}^2}{\|\mathbf{v}_n\|_2^4} \sum_{i=1}^{n-1} \alpha_{i,n}^2 \rightarrow 0, \end{aligned} \tag{3.7}$$

which concludes the proof. \square

Table 3.2

Illustration of Theorems 3.1 and 3.2 in the case $\varepsilon = 4$ and $\varphi = -2$ where $\varepsilon + \varepsilon^{-1} = 4.25$ and $\varphi + \varphi^{-1} = -2.5$. For every n we have denoted by μ_n, ν_n the unique two outliers of $T_{n,\varepsilon,\varphi}$ and by $\mathbf{x}_n, \mathbf{y}_n$ the corresponding normalized eigenvectors computed by JULIA. We have called μ_n the outlier closest to $\varepsilon + \varepsilon^{-1}$ and ν_n the other outlier.

n	outlier μ_n outlier ν_n	$ \mu_n - (\varepsilon + \varepsilon^{-1}) $ $ \nu_n - (\varphi + \varphi^{-1}) $	$\ \mathbf{x}_n - P_{\mathbf{v}_n} \mathbf{x}_n\ _2$ $\ \mathbf{y}_n - P_{\mathbf{w}_n} \mathbf{y}_n\ _2$
8	4.2499999950887285 -2.4999484772090417	$4.9 \cdot 10^{-9}$ $5.2 \cdot 10^{-5}$	$2.3 \cdot 10^{-5}$ $5.9 \cdot 10^{-3}$
16	4.2500000000000000 -2.499999992141966	$1.1 \cdot 10^{-18}$ $7.9 \cdot 10^{-10}$	$3.5 \cdot 10^{-10}$ $2.3 \cdot 10^{-5}$
32	4.2500000000000000 -2.5000000000000000	$6.2 \cdot 10^{-38}$ $1.8 \cdot 10^{-19}$	$8.1 \cdot 10^{-20}$ $3.5 \cdot 10^{-10}$
64	4.2500000000000000 -2.5000000000000000	$1.8 \cdot 10^{-76}$ $9.9 \cdot 10^{-39}$	$4.4 \cdot 10^{-39}$ $8.1 \cdot 10^{-20}$
128	4.2500000000000000 -2.5000000000000000	$1.6 \cdot 10^{-153}$ $2.9 \cdot 10^{-77}$	$1.3 \cdot 10^{-77}$ $4.4 \cdot 10^{-39}$

The next theorem is completely analogous to Theorem 3.1 and can be proved by the same type of argument or by using the relation between $T_{n,\varepsilon,\varphi}$ and $T_{n,\varphi,\varepsilon}$ (see Proposition 2.1).

Theorem 3.2. *Suppose that $|\varphi| > 1$ and $\varepsilon \neq \varphi$. Let (ν_n, \mathbf{y}_n) be an eigenpair of $T_{n,\varepsilon,\varphi}$ such that $\nu_n \rightarrow \varphi + \varphi^{-1}$ as $n \rightarrow \infty$ and $\|\mathbf{y}_n\|_2 = 1$ for all n . Then, the following properties hold.*

1. *Eventually, ν_n is an outlier of $T_{n,\varepsilon,\varphi}$ and any other eigenvalue $\lambda_n \in \sigma(T_{n,\varepsilon,\varphi})$ satisfies $|\lambda_n - (\varphi + \varphi^{-1})| \geq c$ for some positive constant c independent of n .*
2. *$\|\mathbf{y}_n - P_{\mathbf{w}_n} \mathbf{y}_n\|_2 \rightarrow 0$ as $n \rightarrow \infty$, where $\mathbf{w}_n = [\varphi^{-n+1}, \dots, \varphi^{-1}, 1]^\top$.*

To conclude our analysis, we address the case where $|\varepsilon|, |\varphi| > 1$ and $\varepsilon = \varphi$.

Theorem 3.3. *Suppose that $|\varepsilon|, |\varphi| > 1$ and $\varepsilon = \varphi$. Then, the following properties hold.*

1. *There exist exactly two distinct eigenvalues μ_n, ν_n of $T_{n,\varepsilon,\varphi}$ which are eventually the unique two outliers of $T_{n,\varepsilon,\varphi}$ and satisfy $\mu_n, \nu_n \rightarrow \varepsilon + \varepsilon^{-1} = \varphi + \varphi^{-1}$.*
2. *Let \mathbf{x}_n and \mathbf{y}_n be eigenvectors of $T_{n,\varepsilon,\varphi}$ associated with μ_n and ν_n , respectively, and satisfying $\|\mathbf{x}_n\|_2 = \|\mathbf{y}_n\|_2 = 1$ for all n . Then, up to a renaming of μ_n and ν_n , we eventually have $E_n \mathbf{x}_n = \mathbf{x}_n$ and $E_n \mathbf{y}_n = -\mathbf{y}_n$. Moreover, $\|\mathbf{x}_n - P_{\mathbf{v}_n + \mathbf{w}_n} \mathbf{x}_n\|_2 \rightarrow 0$ and $\|\mathbf{y}_n - P_{\mathbf{v}_n - \mathbf{w}_n} \mathbf{y}_n\|_2 \rightarrow 0$ as $n \rightarrow \infty$, where $\mathbf{v}_n = [1, \varepsilon^{-1}, \dots, \varepsilon^{-n+1}]^\top$ and $\mathbf{w}_n = [\varphi^{-n+1}, \dots, \varphi^{-1}, 1]^\top = E_n \mathbf{v}_n$.*

Proof. 1. We first recall that all eigenvalues of $T_{n,\varepsilon,\varphi}$ are distinct by Proposition 2.1. Also, an eigenvalue converging to $\varepsilon + \varepsilon^{-1}$ exists for sure by Lemma 3.1 and more than two eigenvalues converging to $\varepsilon + \varepsilon^{-1}$ cannot exist by Proposition 2.1 as $\varepsilon + \varepsilon^{-1} \notin [-2, 2]$.

Suppose by contradiction that there exists a unique eigenvalue μ_n converging to $\varepsilon + \varepsilon^{-1}$ and let \mathbf{x}_n be a corresponding eigenvector with $\|\mathbf{x}_n\|_2 = 1$. Let $\{\mathbf{u}_{1,n}, \dots, \mathbf{u}_{n,n} = \mathbf{x}_n\}$ be an orthonormal basis of \mathbb{R}^n formed by eigenvectors of $T_{n,\varepsilon,\varphi}$ with corresponding eigenvalues $\lambda_{1,n}, \dots, \lambda_{n,n} = \mu_n$:

$$T_{n,\varepsilon,\varphi} \mathbf{u}_{i,n} = \lambda_{i,n} \mathbf{u}_{i,n}, \quad i = 1, \dots, n.$$

We expand the vector \mathbf{v}_n on this basis as in (3.1) and we get (3.2)–(3.4). Since μ_n is the unique eigenvalue of $T_{n,\varepsilon,\varphi}$ converging to $\varepsilon + \varepsilon^{-1} \notin [-2, 2]$ and $n - 2$ eigenvalues of $T_{n,\varepsilon,\varphi}$ belong to $[-2, 2]$ for all n , there exists a positive constant c independent of n such that

$$\sum_{i=1}^n (\lambda_{i,n} - (\varepsilon + \varepsilon^{-1}))^2 \alpha_{i,n}^2 \geq c^2 \sum_{i=1}^{n-1} \alpha_{i,n}^2 + (\mu_n - (\varepsilon + \varepsilon^{-1}))^2 \alpha_{n,n}^2 \tag{3.8}$$

frequently as $n \rightarrow \infty$. Passing to a subsequence of indices n , if necessary, we may assume that (3.8) is satisfied for all n . Note that (3.8) is the same as (3.5). Hence, by reasoning as before, we infer that (3.6)–(3.7) hold and we conclude that $\|\mathbf{x}_n - P_{\mathbf{v}_n} \mathbf{x}_n\|_2 \rightarrow 0$ (for the considered subsequence of indices n). This is impossible for the following reasons.

- Since $\varepsilon = \varphi$, we have $T_{n,\varepsilon,\varphi} = T_{n,\varphi,\varepsilon}$ and, by Proposition 2.1, (λ, \mathbf{u}) is an eigenpair of $T_{n,\varepsilon,\varphi}$ if and only if the same is true for $(\lambda, E_n \mathbf{u})$.
- By Proposition 2.1, each eigenvalue λ of $T_{n,\varepsilon,\varphi}$ is simple and so $E_n \mathbf{u} = \pm \mathbf{u}$ for all eigenvectors \mathbf{u} of $T_{n,\varepsilon,\varphi}$. In particular $E_n \mathbf{x}_n = \pm \mathbf{x}_n$ for all n .
- If $\|\mathbf{x}_n - P_{\mathbf{v}_n} \mathbf{x}_n\|_2 \rightarrow 0$, then the relation $E_n \mathbf{x}_n = \pm \mathbf{x}_n$ cannot hold for all n . Indeed, considering that $P_{\mathbf{v}_n} \mathbf{x}_n = c_n \mathbf{v}_n$ is a multiple of \mathbf{v}_n , from $\|\mathbf{x}_n - P_{\mathbf{v}_n} \mathbf{x}_n\|_2 \rightarrow 0$ and $\|\mathbf{x}_n\|_2 = 1$ we deduce that $\|P_{\mathbf{v}_n} \mathbf{x}_n\|_2 = |c_n| \|\mathbf{v}_n\|_2 \rightarrow 1$, i.e., $c_n \rightarrow 1 - \varepsilon^{-2}$ (see (3.2)), and

$$\begin{aligned} |(\mathbf{x}_n)_1 - (P_{\mathbf{v}_n} \mathbf{x}_n)_1| &= |(\mathbf{x}_n)_1 - c_n| \rightarrow 0, \\ |(\mathbf{x}_n)_n - (P_{\mathbf{v}_n} \mathbf{x}_n)_n| &= |(\mathbf{x}_n)_n - c_n \varepsilon^{-n+1}| \rightarrow 0, \end{aligned}$$

which are clearly incompatible with $E_n \mathbf{x}_n = \pm \mathbf{x}_n$ as the latter implies $(\mathbf{x}_n)_n = \pm (\mathbf{x}_n)_1$.

2. Let $\{\mathbf{u}_{1,n}, \dots, \mathbf{u}_{n-1,n} = \mathbf{x}_n, \mathbf{u}_{n,n} = \mathbf{y}_n\}$ be an orthonormal basis of \mathbb{R}^n formed by eigenvectors of $T_{n,\varepsilon,\varphi}$ with corresponding eigenvalues $\lambda_{1,n}, \dots, \lambda_{n-1,n} = \mu_n, \lambda_{n,n} = \nu_n$:

$$T_{n,\varepsilon,\varphi} \mathbf{u}_{i,n} = \lambda_{i,n} \mathbf{u}_{i,n}, \quad i = 1, \dots, n.$$

Expand the vectors $\mathbf{v}_n + \mathbf{w}_n$ and $\mathbf{v}_n - \mathbf{w}_n$ on this basis:

$$\mathbf{v}_n + \mathbf{w}_n = \sum_{i=1}^n \rho_{i,n} \mathbf{u}_{i,n}, \tag{3.9}$$

$$\mathbf{v}_n - \mathbf{w}_n = \sum_{i=1}^n \tau_{i,n} \mathbf{u}_{i,n}, \tag{3.10}$$

$$\sum_{i=1}^n \rho_{i,n}^2 = \|\mathbf{v}_n + \mathbf{w}_n\|_2^2 = 2 \frac{1 - \varepsilon^{-2n}}{1 - \varepsilon^{-2}} + 2n\varepsilon^{-n+1} \rightarrow \frac{2}{1 - \varepsilon^{-2}}, \tag{3.11}$$

$$\sum_{i=1}^n \tau_{i,n}^2 = \|\mathbf{v}_n - \mathbf{w}_n\|_2^2 = 2 \frac{1 - \varepsilon^{-2n}}{1 - \varepsilon^{-2}} - 2n\varepsilon^{-n+1} \rightarrow \frac{2}{1 - \varepsilon^{-2}}. \tag{3.12}$$

Keeping in mind that $\varepsilon = \varphi$, the equations

$$\begin{aligned} T_{n,\varepsilon,\varphi} \mathbf{v}_n - (\varepsilon + \varepsilon^{-1}) \mathbf{v}_n &= \varepsilon^{-n}(\varepsilon\varphi - 1) \mathbf{e}_n, \\ T_{n,\varepsilon,\varphi} \mathbf{w}_n - (\varphi + \varphi^{-1}) \mathbf{w}_n &= \varphi^{-n}(\varepsilon\varphi - 1) \mathbf{e}_1 \end{aligned}$$

in Proposition 2.1 yield

$$\begin{aligned} T_{n,\varepsilon,\varphi}(\mathbf{v}_n + \mathbf{w}_n) - (\varepsilon + \varepsilon^{-1})(\mathbf{v}_n + \mathbf{w}_n) &= \varepsilon^{-n}(\varepsilon\varphi - 1)(\mathbf{e}_n + \mathbf{e}_1), \\ T_{n,\varepsilon,\varphi}(\mathbf{v}_n - \mathbf{w}_n) - (\varepsilon + \varepsilon^{-1})(\mathbf{v}_n - \mathbf{w}_n) &= \varepsilon^{-n}(\varepsilon\varphi - 1)(\mathbf{e}_n - \mathbf{e}_1), \end{aligned}$$

i.e.,

$$\begin{aligned} \sum_{i=1}^n (\lambda_{i,n} - (\varepsilon + \varepsilon^{-1})) \rho_{i,n} \mathbf{u}_{i,n} &= \varepsilon^{-n}(\varepsilon\varphi - 1)(\mathbf{e}_n + \mathbf{e}_1), \\ \sum_{i=1}^n (\lambda_{i,n} - (\varepsilon + \varepsilon^{-1})) \tau_{i,n} \mathbf{u}_{i,n} &= \varepsilon^{-n}(\varepsilon\varphi - 1)(\mathbf{e}_n - \mathbf{e}_1). \end{aligned}$$

Passing to the norms, we obtain

$$\sum_{i=1}^n (\lambda_{i,n} - (\varepsilon + \varepsilon^{-1}))^2 \rho_{i,n}^2 = 2\varepsilon^{-2n}(\varepsilon\varphi - 1)^2 \rightarrow 0, \tag{3.13}$$

$$\sum_{i=1}^n (\lambda_{i,n} - (\varepsilon + \varepsilon^{-1}))^2 \tau_{i,n}^2 = 2\varepsilon^{-2n}(\varepsilon\varphi - 1)^2 \rightarrow 0. \tag{3.14}$$

Since μ_n, ν_n are eventually the unique two outliers of $T_{n,\varepsilon,\varphi}$, the other $n - 2$ eigenvalues $\lambda_{1,n}, \dots, \lambda_{n-2,n}$ eventually belong to $[-2, 2]$ and from (3.11)–(3.14) we infer that

$$\sum_{i=1}^{n-2} \rho_{i,n}^2 \rightarrow 0, \quad \rho_{n-1,n}^2 + \rho_{n,n}^2 \rightarrow \frac{2}{1 - \varepsilon^{-2}}, \tag{3.15}$$

$$\sum_{i=1}^{n-2} \tau_{i,n}^2 \rightarrow 0, \quad \tau_{n-1,n}^2 + \tau_{n,n}^2 \rightarrow \frac{2}{1 - \varepsilon^{-2}}. \tag{3.16}$$

Table 3.3

Illustration of Theorem 3.3 in the case $\varepsilon = \varphi = 8/5$ where $\varepsilon + \varepsilon^{-1} = \varphi + \varphi^{-1} = 2.225$. For every n we have denoted by μ_n, ν_n the unique two outliers of $T_{n,\varepsilon,\varphi}$ and by $\mathbf{x}_n, \mathbf{y}_n$ the corresponding normalized eigenvectors computed by JULIA. We have called μ_n the outlier whose eigenvector \mathbf{x}_n is the closest to its projection onto $\langle \mathbf{v}_n + \mathbf{w}_n \rangle$ and ν_n the other outlier. We have numerically verified that, up to rounding errors, $E_n \mathbf{x}_n = \mathbf{x}_n$ and $E_n \mathbf{y}_n = -\mathbf{y}_n$ for all the considered n .

n	outlier μ_n	$ \mu_n - (\varepsilon + \varepsilon^{-1}) $	$\ \mathbf{x}_n - P_{\mathbf{v}_n + \mathbf{w}_n} \mathbf{x}_n\ _2$
	outlier ν_n	$ \nu_n - (\varphi + \varphi^{-1}) $	$\ \mathbf{y}_n - P_{\mathbf{v}_n - \mathbf{w}_n} \mathbf{y}_n\ _2$
8	2.2447548446486838	$2.0 \cdot 10^{-2}$	$2.1 \cdot 10^{-2}$
	2.1991364375014231	$2.6 \cdot 10^{-2}$	$1.2 \cdot 10^{-2}$
16	2.2255116405185864	$5.1 \cdot 10^{-4}$	$5.9 \cdot 10^{-4}$
	2.2244808853312168	$5.2 \cdot 10^{-5}$	$4.9 \cdot 10^{-4}$
32	2.2250002793612006	$2.8 \cdot 10^{-7}$	$2.9 \cdot 10^{-7}$
	2.2249997206340419	$2.8 \cdot 10^{-7}$	$2.9 \cdot 10^{-7}$
64	2.2250000000000821	$8.2 \cdot 10^{-14}$	$8.6 \cdot 10^{-14}$
	2.2249999999999180	$8.2 \cdot 10^{-14}$	$8.6 \cdot 10^{-14}$
128	2.2250000000000000	$7.1 \cdot 10^{-27}$	$7.5 \cdot 10^{-27}$
	2.2250000000000000	$7.1 \cdot 10^{-27}$	$7.5 \cdot 10^{-27}$

Now, recall from the proof of item 1 that (in the present case where $\varepsilon = \varphi$) all eigenvectors \mathbf{u} of $T_{n,\varepsilon,\varphi}$ satisfy $E_n \mathbf{u} = \pm \mathbf{u}$. Since $E_n(\mathbf{v}_n + \mathbf{w}_n) = \mathbf{v}_n + \mathbf{w}_n$ and $E(\mathbf{v}_n - \mathbf{w}_n) = -(\mathbf{v}_n - \mathbf{w}_n)$, for the eigenvectors $\mathbf{u}_{i,n}$ satisfying $E_n \mathbf{u}_{i,n} = \mathbf{u}_{i,n}$ we have $\tau_{i,n} = 0$ in the expansion (3.10), and for the eigenvectors $\mathbf{u}_{i,n}$ satisfying $E_n \mathbf{u}_{i,n} = -\mathbf{u}_{i,n}$ we have $\rho_{i,n} = 0$ in the expansion (3.9). It follows that, eventually, one among \mathbf{x}_n and \mathbf{y}_n (say \mathbf{x}_n) must satisfy $E_n \mathbf{x}_n = \mathbf{x}_n$ and the other (say \mathbf{y}_n) must satisfy the “opposite” equation $E_n \mathbf{y}_n = -\mathbf{y}_n$. Indeed, if we frequently had $E_n \mathbf{x}_n = \mathbf{x}_n$ and $E_n \mathbf{y}_n = \mathbf{y}_n$, then we would also have $\tau_{n-1,n} = \tau_{n,n} = 0$ frequently, which is impossible by (3.16). Similarly, if we frequently had $E_n \mathbf{x}_n = -\mathbf{x}_n$ and $E_n \mathbf{y}_n = -\mathbf{y}_n$, then we would also have $\rho_{n-1,n} = \rho_{n,n} = 0$ frequently, which is impossible by (3.15). By renaming μ_n and ν_n (if necessary), we can assume that the eigenvector \mathbf{x}_n associated with μ_n eventually satisfies $E_n \mathbf{x}_n = \mathbf{x}_n$, and the eigenvector \mathbf{y}_n associated with ν_n eventually satisfies $E_n \mathbf{y}_n = -\mathbf{y}_n$. In particular, we eventually have

$$\rho_{n,n} = 0, \tag{3.17}$$

$$\tau_{n-1,n} = 0. \tag{3.18}$$

Thus, by applying (3.9), (3.11), (3.15) and (3.17), we eventually obtain

$$\begin{aligned} \|\mathbf{x}_n - P_{\mathbf{v}_n + \mathbf{w}_n} \mathbf{x}_n\|_2^2 &= \|\mathbf{u}_{n-1,n} - P_{\mathbf{v}_n + \mathbf{w}_n} \mathbf{u}_{n-1,n}\|_2^2 \\ &= \left\| \mathbf{u}_{n-1,n} - \frac{(\mathbf{u}_{n-1,n}, \mathbf{v}_n + \mathbf{w}_n)}{(\mathbf{v}_n + \mathbf{w}_n, \mathbf{v}_n + \mathbf{w}_n)} (\mathbf{v}_n + \mathbf{w}_n) \right\|_2^2 \\ &= \left\| \mathbf{u}_{n-1,n} - \frac{\rho_{n-1,n}}{\|\mathbf{v}_n + \mathbf{w}_n\|_2^2} \sum_{i=1}^n \rho_{i,n} \mathbf{u}_{i,n} \right\|_2^2 \end{aligned}$$

$$\begin{aligned}
 &= \left\| \left(1 - \frac{\rho_{n-1,n}^2}{\|\mathbf{v}_n + \mathbf{w}_n\|_2^2} \right) \mathbf{u}_{n-1,n} - \frac{\rho_{n-1,n}}{\|\mathbf{v}_n + \mathbf{w}_n\|_2^2} \sum_{i=1}^{n-2} \rho_{i,n} \mathbf{u}_{i,n} \right\|_2^2 \\
 &= \left(1 - \frac{\rho_{n-1,n}^2}{\|\mathbf{v}_n + \mathbf{w}_n\|_2^2} \right)^2 + \frac{\rho_{n-1,n}^2}{\|\mathbf{v}_n + \mathbf{w}_n\|_2^4} \sum_{i=1}^{n-2} \rho_{i,n}^2 \rightarrow 0.
 \end{aligned}$$

Similarly, one can show that $\|\mathbf{y}_n - P_{\mathbf{v}_n - \mathbf{w}_n} \mathbf{y}_n\|_2^2 \rightarrow 0$. \square

In Tables 3.1–3.3, we illustrate through numerical experiments the results presented in Theorems 3.1–3.3. The experiments have been performed via the high-performance computing language JULIA [6] with a machine precision equal to $1.1 \cdot 10^{-308}$ (1024-bit precision). We note that the convergences predicted by Theorems 3.1–3.3 are quite fast. Actually, this could be expected on the basis of Property 2 in Proposition 2.1, where we see that for $|\varepsilon|, |\varphi| > 1$ the pairs $(\varepsilon + \varepsilon^{-1}, \mathbf{v}_n)$ and $(\varphi + \varphi^{-1}, \mathbf{w}_n)$ are substantially eigenpairs of $T_{n,\varepsilon,\varphi}$ already for moderate n due to the exponential convergence to 0 of the error terms $\varepsilon^{-n}(\varepsilon\varphi - 1)\mathbf{e}_n$ and $\varphi^{-n}(\varepsilon\varphi - 1)\mathbf{e}_1$.

4. Equations for the eigenvalues and eigenvectors of $T_{n,\varepsilon,\varphi}$

In this section, we derive equations for the eigenvalues of $T_{n,\varepsilon,\varphi}$. As we shall see, the equations for the outliers are formally the same as the equations for the non-outliers with the only difference that the trigonometric functions $\sin x$ and $\cos x$ must be replaced by the corresponding hyperbolic functions $\sinh x$ and $\cosh x$. For all $\varepsilon, \varphi \in \mathbb{R}$ for which these equations can be solved, one obtains not only the eigenvalues but also the eigenvectors of $T_{n,\varepsilon,\varphi}$. It should be noted that the results presented in this section have already been obtained in a more general framework by Losonczi [26], though with a different approach and without a focus on the outliers; in particular, Losonczi does not introduce the hyperbolic functions $\sinh x$ and $\cosh x$. A special role in the following derivation is played by the theory of linear difference equations [24].

Let $\lambda \in \mathbb{R}$ and $\mathbf{v} \in \mathbb{C}^n \setminus \{\mathbf{0}\}$, so that (λ, \mathbf{v}) is a candidate eigenpair for the real symmetric matrix $T_{n,\varepsilon,\varphi}$. We have

$$\begin{aligned}
 T_{n,\varepsilon,\varphi} \mathbf{v} = \lambda \mathbf{v} &\iff \begin{cases} \varepsilon v_1 + v_2 = \lambda v_1 \\ v_{i-1} + v_{i+1} = \lambda v_i \text{ for all } i = 2, \dots, n-1 \\ v_{n-1} + \varphi v_n = \lambda v_n \end{cases} \\
 &\iff \text{exists a sequence } (w_0, w_1, \dots) \text{ such that } w_i = v_i \text{ for } i = 1, \dots, n \text{ and} \\
 &\quad \begin{cases} w_0 = \varepsilon w_1 \\ w_{i-1} + w_{i+1} = \lambda w_i \text{ for all } i \geq 1 \\ w_{n+1} = \varphi w_n \end{cases} \tag{4.1}
 \end{aligned}$$

The characteristic equation of the linear difference equation (4.1) is given by

$$x^2 - \lambda x + 1 = 0. \tag{4.2}$$

We consider five different cases.

4.1. Case 1: $\lambda \in (-2, 2)$

In this case, we set $\lambda = 2 \cos \theta$ with $\theta \in (0, \pi)$. The roots of the characteristic equation (4.2) are given by

$$\frac{\lambda \pm \sqrt{\lambda^2 - 4}}{2} = \frac{2 \cos \theta \pm 2i \sin \theta}{2} = e^{\pm i\theta},$$

and they are distinct because $\theta \in (0, \pi)$. The general solution of (4.1) is given by

$$w_i = Ae^{i\theta} + Be^{-i\theta} \text{ for all } i \geq 0,$$

where $A, B \in \mathbb{C}$ are arbitrary constants. Keeping in mind that $\mathbf{v} \neq \mathbf{0}$, we have

$T_{n,\varepsilon,\varphi} \mathbf{v} = \lambda \mathbf{v} \iff$ exists a sequence (w_0, w_1, \dots) such that $w_i = v_i$ for $i = 1, \dots, n$ and

$$\begin{aligned} & \begin{cases} w_i = Ae^{i\theta} + Be^{-i\theta} \text{ for all } i \geq 0 \\ A + B = \varepsilon Ae^{i\theta} + \varepsilon Be^{-i\theta} \\ Ae^{i(n+1)\theta} + Be^{-i(n+1)\theta} = \varphi Ae^{in\theta} + \varphi Be^{-in\theta} \end{cases} \\ \iff & \begin{cases} v_i = Ae^{i\theta} + Be^{-i\theta} \text{ for all } i = 1, \dots, n \\ A = \frac{\varepsilon e^{-i\theta} - 1}{1 - \varepsilon e^{i\theta}} B \quad (1 - \varepsilon e^{i\theta} \neq 0 \text{ because } \theta \in (0, \pi)) \\ 0 = \begin{vmatrix} 1 - \varepsilon e^{i\theta} & 1 - \varepsilon e^{-i\theta} \\ e^{in\theta}(e^{i\theta} - \varphi) & e^{-in\theta}(e^{-i\theta} - \varphi) \end{vmatrix} \end{cases} \\ \iff & \begin{cases} v_i = B \left(\frac{\varepsilon e^{-i\theta} - 1}{1 - \varepsilon e^{i\theta}} e^{ii\theta} + e^{-ii\theta} \right) \\ = \frac{2iB}{\varepsilon e^{i\theta} - 1} \left(\sin(i\theta) - \varepsilon \sin((i-1)\theta) \right) \text{ for all } i = 1, \dots, n \\ 0 = \sin((n+1)\theta) - (\varepsilon + \varphi) \sin(n\theta) + \varepsilon \varphi \sin((n-1)\theta) \end{cases} \end{aligned}$$

We summarize in the next theorem the result that we have obtained.

Theorem 4.1. For every $\theta \in (0, \pi)$, the number $\lambda = 2 \cos \theta$ is an eigenvalue of $T_{n,\varepsilon,\varphi}$ if and only if

$$\sin((n+1)\theta) - (\varepsilon + \varphi) \sin(n\theta) + \varepsilon \varphi \sin((n-1)\theta) = 0. \tag{4.3}$$

In this case, a corresponding eigenvector $\mathbf{v} = (v_1, \dots, v_n)$ is given by

$$v_i = \sin(i\theta) - \varepsilon \sin((i - 1)\theta), \quad i = 1, \dots, n.$$

4.2. Case 2: $\lambda \in (2, \infty)$

In this case, we set $\lambda = 2 \cosh \theta$ with $\theta \in (0, \infty)$. The roots of the characteristic equation (4.2) are given by

$$\frac{\lambda \pm \sqrt{\lambda^2 - 4}}{2} = \frac{2 \cosh \theta \pm 2 \sinh \theta}{2} = e^{\pm \theta},$$

and they are distinct because $\theta \in (0, \infty)$. The general solution of (4.1) is given by

$$w_i = Ae^{i\theta} + Be^{-i\theta} \text{ for all } i \geq 0,$$

where $A, B \in \mathbb{C}$ are arbitrary constants. Keeping in mind that $\mathbf{v} \neq \mathbf{0}$, we have

$T_{n,\varepsilon,\varphi}\mathbf{v} = \lambda\mathbf{v} \iff$ exists a sequence (w_0, w_1, \dots) such that $w_i = v_i$ for $i = 1, \dots, n$ and

$$\begin{aligned} & \left\{ \begin{array}{l} w_i = Ae^{i\theta} + Be^{-i\theta} \text{ for all } i \geq 0 \\ A + B = \varepsilon Ae^\theta + \varepsilon Be^{-\theta} \\ Ae^{(n+1)\theta} + Be^{-(n+1)\theta} = \varphi Ae^{n\theta} + \varphi Be^{-n\theta} \end{array} \right. \\ \iff & \left\{ \begin{array}{l} v_i = Ae^{i\theta} + Be^{-i\theta} \text{ for all } i = 1, \dots, n \\ A + B = \varepsilon Ae^\theta + \varepsilon Be^{-\theta} \\ \text{(this equation is not identically 0 because} \\ 1 - \varepsilon e^\theta = 0 \implies 1 - \varepsilon e^{-\theta} \neq 0) \\ 0 = \begin{vmatrix} 1 - \varepsilon e^\theta & 1 - \varepsilon e^{-\theta} \\ e^{n\theta}(e^\theta - \varphi) & e^{-n\theta}(e^{-\theta} - \varphi) \end{vmatrix} \end{array} \right. \\ \iff & \left\{ \begin{array}{l} v_i = Ae^{i\theta} + Be^{-i\theta} \text{ for all } i = 1, \dots, n \\ A + B = \varepsilon Ae^\theta + \varepsilon Be^{-\theta} \\ 0 = \sinh((n + 1)\theta) - (\varepsilon + \varphi) \sinh(n\theta) + \varepsilon\varphi \sinh((n - 1)\theta) \end{array} \right. \end{aligned}$$

- If $1 - \varepsilon e^\theta = 0$, i.e., $e^{-\theta} = \varepsilon$, then the equation $A + B = \varepsilon Ae^\theta + \varepsilon Be^{-\theta}$ is equivalent to $B = 0$ and so

$$T_{n,\varepsilon,\varphi}\mathbf{v} = \lambda\mathbf{v} \iff \begin{cases} v_i = Ae^{i\theta} = A\varepsilon^{-i} \text{ for all } i = 1, \dots, n \\ 0 = \sinh((n + 1)\theta) - (\varepsilon + \varphi) \sinh(n\theta) + \varepsilon\varphi \sinh((n - 1)\theta) \end{cases}$$

- If $1 - \varepsilon e^\theta \neq 0$, then the equation $A + B = \varepsilon Ae^\theta + \varepsilon Be^{-\theta}$ is equivalent to $A = \frac{\varepsilon e^{-\theta} - 1}{1 - \varepsilon e^\theta} B$ and so

$$T_{n,\varepsilon,\varphi} \mathbf{v} = \lambda \mathbf{v} \iff \begin{cases} v_i = B \left(\frac{\varepsilon e^{-\theta} - 1}{1 - \varepsilon e^\theta} e^{i\theta} + e^{-i\theta} \right) \\ = \frac{2B}{\varepsilon e^\theta - 1} \left(\sinh(i\theta) - \varepsilon \sinh((i-1)\theta) \right) \text{ for all } i = 1, \dots, n \\ 0 = \sinh((n+1)\theta) - (\varepsilon + \varphi) \sinh(n\theta) + \varepsilon \varphi \sinh((n-1)\theta) \end{cases}$$

As often happens in mathematics, the “limit” case $1 - \varepsilon e^\theta = 0$ merges with the case $1 - \varepsilon e^\theta \neq 0$. Indeed, if $1 - \varepsilon e^\theta = 0$, then $\varepsilon = e^{-\theta} \in (0, 1)$ (because $\theta \in (0, \infty)$) and

$$\sinh(i\theta) - \varepsilon \sinh((i-1)\theta) = \frac{1 - \varepsilon^2}{2} \varepsilon^{-i}, \quad i = 1, \dots, n.$$

We summarize in the next theorem the result that we have obtained.

Theorem 4.2. *For every $\theta \in (0, \infty)$, the number $\lambda = 2 \cosh \theta$ is an eigenvalue of $T_{n,\varepsilon,\varphi}$ if and only if*

$$\sinh((n+1)\theta) - (\varepsilon + \varphi) \sinh(n\theta) + \varepsilon \varphi \sinh((n-1)\theta) = 0. \tag{4.4}$$

In this case, a corresponding eigenvector $\mathbf{v} = (v_1, \dots, v_n)$ is given by

$$v_i = \sinh(i\theta) - \varepsilon \sinh((i-1)\theta), \quad i = 1, \dots, n.$$

4.3. Case 3: $\lambda = 2$

In this case, the characteristic equation (4.2) has only one root $x = 1$ with multiplicity 2. The general solution of (4.1) is given by

$$w_i = A + Bi \text{ for all } i \geq 0,$$

where $A, B \in \mathbb{C}$ are arbitrary constants. Following the same line of argument as in Sections 4.1–4.2, we obtain the following result.

Theorem 4.3. *The number $\lambda = 2$ is an eigenvalue of $T_{n,\varepsilon,\varphi}$ if and only if*

$$n + 1 - (\varepsilon + \varphi)n + \varepsilon \varphi(n - 1) = 0. \tag{4.5}$$

In this case, a corresponding eigenvector $\mathbf{v} = (v_1, \dots, v_n)$ is given by

$$v_i = \varepsilon + (1 - \varepsilon)i, \quad i = 1, \dots, n.$$

4.4. Case 4: $\lambda \in (-\infty, -2)$

In this case, we set $\lambda = -2 \cosh \theta$ with $\theta \in (0, \infty)$. The derivation is essentially the same as in Section 4.2; we leave the details to the reader and we report the analog of Theorem 4.2.

Theorem 4.4. *For every $\theta \in (0, \infty)$, the number $\lambda = -2 \cosh \theta$ is an eigenvalue of $T_{n,\varepsilon,\varphi}$ if and only if*

$$\sinh((n + 1)\theta) + (\varepsilon + \varphi) \sinh(n\theta) + \varepsilon\varphi \sinh((n - 1)\theta) = 0. \tag{4.6}$$

In this case, a corresponding eigenvector $\mathbf{v} = (v_1, \dots, v_n)$ is given by

$$v_i = (-1)^i (\sinh(i\theta) + \varepsilon \sinh((i - 1)\theta)), \quad i = 1, \dots, n.$$

4.5. Case 5: $\lambda = -2$

The derivation is essentially the same as in Section 4.3; we leave the details to the reader and we report the analog of Theorem 4.3.

Theorem 4.5. *The number $\lambda = -2$ is an eigenvalue of $T_{n,\varepsilon,\varphi}$ if and only if*

$$n + 1 + (\varepsilon + \varphi)n + \varepsilon\varphi(n - 1) = 0. \tag{4.7}$$

In this case, a corresponding eigenvector $\mathbf{v} = (v_1, \dots, v_n)$ is given by

$$v_i = (-1)^i (-\varepsilon + (1 + \varepsilon)i), \quad i = 1, \dots, n.$$

5. Eigendecomposition of $T_{n,\varepsilon,\varphi}$ for specific choices of ε and φ

5.1. $\varepsilon, \varphi \in \{0, 1, -1\}$

As noted in the introduction, the eigendecomposition of $T_{n,\varepsilon,\varphi}$ for $\varepsilon, \varphi \in \{0, 1, -1\}$ is already available in the literature. The purpose of this section is simply to show that it can also be obtained from Theorems 4.1, 4.3, and 4.5. Note that Theorems 4.2 and 4.4 are useless in this case as $T_{n,\varepsilon,\varphi}$ does not have outliers for $\varepsilon, \varphi \in \{0, 1, -1\}$; see Proposition 2.1.

For $(\varepsilon, \varphi) = (0, 0)$, Theorem 4.1 immediately yields the eigenpairs $(\lambda_k, \mathbf{v}^{(k)})$, $k = 1, \dots, n$, with

$$\lambda_k = 2 \cos \theta_k, \quad \mathbf{v}^{(k)} = [\sin(i\theta_k)]_{i=1}^n, \quad \theta_k = \frac{k\pi}{n + 1}.$$

For $(\varepsilon, \varphi) = (1, 1)$, using sine addition/subtraction formulas, we see that equation (4.3) is equivalent to

$$\sin(n\theta)(2 \cos \theta - 2) = 0,$$

whose solutions in $(0, \pi)$ are $\theta_k = \frac{k\pi}{n}$, $k = 1, \dots, n - 1$; moreover, equation (4.5) is satisfied. Since, by prosthaphaeresis formulas,

$$\sin(i\theta) - \sin((i - 1)\theta) = 2 \sin \frac{\theta}{2} \cos \frac{(2i - 1)\theta}{2},$$

we conclude by Theorems 4.1 and 4.3 that, for $(\varepsilon, \varphi) = (1, 1)$, a complete set of eigenpairs for $T_{n,\varepsilon,\varphi} = T_{n,1,1}$ is given by $(\lambda_k, \mathbf{v}^{(k)})$, $k = 0, \dots, n - 1$, with

$$\lambda_k = 2 \cos \theta_k, \quad \mathbf{v}^{(k)} = \left[\cos \frac{(2i - 1)\theta_k}{2} \right]_{i=1}^n, \quad \theta_k = \frac{k\pi}{n}.$$

Similar derivations, using sine addition/subtraction and prosthaphaeresis formulas, can be done for all $\varepsilon, \varphi \in \{0, 1, -1\}$; we leave the details to the reader.

5.2. $\varepsilon\varphi = 1$

We focus in this section on the case $\varepsilon\varphi = 1$, which is crucial for the applications presented in Section 6. To the best of the authors’ knowledge, this case has never been addressed in the literature. Besides $\varepsilon\varphi = 1$, we also assume that:

- $\varepsilon, \varphi > 0$ (because no additional difficulties are encountered if $\varepsilon, \varphi < 0$);
- $\varepsilon, \varphi \neq 1$ (because the case $\varepsilon = \varphi = 1$ has already been addressed in Section 5.1).

Under these assumptions, we have

$$\frac{\varepsilon + \varphi}{2} = \frac{\varepsilon + \varepsilon^{-1}}{2} = \cosh(\log \varepsilon) > 1.$$

Using sine addition/subtraction formulas, we see that equation (4.3) is equivalent to

$$\sin(n\theta) \left(\cos \theta - \frac{\varepsilon + \varepsilon^{-1}}{2} \right) = 0,$$

whose solutions in $(0, \pi)$ are $\theta_k = \frac{k\pi}{n}$, $k = 1, \dots, n - 1$. Thus, Theorem 4.1 yields $n - 1$ eigenpairs of $T_{n,\varepsilon,\varphi}$, i.e., $(\lambda_k, \mathbf{v}^{(k)})$, $k = 1, \dots, n - 1$, with

$$\lambda_k = 2 \cos \theta_k, \quad \mathbf{v}^{(k)} = \left[\sin(i\theta_k) - \varepsilon \sin((i - 1)\theta_k) \right]_{i=1}^n, \quad \theta_k = \frac{k\pi}{n}.$$

We still have to find one eigenvalue, which can be neither 2 nor -2 because, under our assumptions, equations (4.5) and (4.7) are not satisfied. In other words, the eigenvalue we are looking for is an outlier. Since equation (4.4) is equivalent to

$$\sinh(n\theta)\left(\cosh\theta - \frac{\varepsilon + \varepsilon^{-1}}{2}\right) = 0,$$

it has a unique solution in $(0, \infty)$ given by $\theta = |\log \varepsilon|$. We then obtain the outlier λ and the corresponding eigenvector \mathbf{v} from Theorem 4.2:

$$\lambda = 2 \cosh \theta, \quad \mathbf{v} = [\sinh(i\theta) - \varepsilon \sinh((i - 1)\theta)]_{i=1}^n, \quad \theta = |\log \varepsilon|.$$

After straightforward manipulations, involving also a renormalization of \mathbf{v} , we get for the outlier eigenpair (λ, \mathbf{v}) the following simplified expressions:

$$\lambda = \varepsilon + \varepsilon^{-1} = \varphi + \varphi^{-1} = \varepsilon + \varphi, \quad \mathbf{v} = [\varepsilon^{-i+1}]_{i=1}^n = [\varphi^{i-1}]_{i=1}^n.$$

Note that this outlier eigenpair could also be obtained from Property 2 of Proposition 2.1. In conclusion, if we set

$$V_{n,\varepsilon} = [\mathbf{v} \mid \mathbf{v}^{(1)} \mid \dots \mid \mathbf{v}^{(n-1)}],$$

then the eigendecomposition of $T_{n,\varepsilon,\varphi}$ is given by

$$T_{n,\varepsilon,\varphi} = V_{n,\varepsilon} \begin{bmatrix} \varepsilon + \varepsilon^{-1} & & & & \\ & 2 \cos \frac{\pi}{n} & & & \\ & & 2 \cos \frac{2\pi}{n} & & \\ & & & \ddots & \\ & & & & 2 \cos \frac{(n-1)\pi}{n} \end{bmatrix} V_{n,\varepsilon}^{-1}.$$

6. Applications

In this section, we present a few applications of our results in the context of Markov chains and processes. Section 6.1 deals with a queuing model. Sections 6.2 and 6.3 are devoted to random walks in unidimensional and multidimensional lattices, respectively. Finally, Sections 6.4 and 6.5 focus on multidimensional reflected diffusion processes and related economics applications.

6.1. Queuing model

Consider a continuous-time Markov chain with n states $0, \dots, n-1$ and with transition rate matrix (infinitesimal generator) given by

$$Q_{n,\lambda,\mu} = \begin{bmatrix} -\lambda & \lambda & & & & \\ \mu & -\lambda - \mu & \lambda & & & \\ & \ddots & \ddots & \ddots & & \\ & & & \mu & -\lambda - \mu & \lambda \\ & & & & \mu & -\mu \end{bmatrix}, \tag{6.1}$$

where $\lambda, \mu > 0$. Markov chains of this kind are referred to as M/M/1/K queues (with $K = n - 1$). They find applications in queuing theory [7,22,25], especially in telecommunications [22, Section 5.7]. In this section, we derive the eigendecomposition of $Q_{n,\lambda,\mu}^\top$. Note that for $\lambda = \mu$ the eigendecomposition is already known [13,26]. We begin with the following lemma, which can be proved by direct computation; see also [28].

Lemma 6.1. *Let*

$$T = \begin{bmatrix} a_1 & b_1 & & & & \\ c_1 & a_2 & b_2 & & & \\ & c_2 & \ddots & \ddots & & \\ & & \ddots & \ddots & b_{n-1} & \\ & & & c_{n-1} & a_n & \end{bmatrix}$$

be a real tridiagonal matrix such that $b_i c_i > 0$ for all $i = 1, \dots, n - 1$. Then

$$T = D \begin{bmatrix} a_1 & \sqrt{b_1 c_1} & & & & \\ \sqrt{b_1 c_1} & a_2 & \sqrt{b_2 c_2} & & & \\ & \sqrt{b_2 c_2} & \ddots & \ddots & & \\ & & \ddots & \ddots & \sqrt{b_{n-1} c_{n-1}} & \\ & & & \sqrt{b_{n-1} c_{n-1}} & a_n & \end{bmatrix} D^{-1},$$

where $D = \text{diag}\left(1, \sqrt{\frac{c_1}{b_1}}, \sqrt{\frac{c_1 c_2}{b_1 b_2}}, \dots, \sqrt{\frac{c_1 \cdots c_{n-1}}{b_1 \cdots b_{n-1}}}\right)$.

By applying Lemma 6.1 to the matrix $Q_{n,\lambda,\mu}^\top$, we obtain

$$Q_{n,\lambda,\mu}^\top = D_{n,\lambda,\mu} X_{n,\lambda,\mu} D_{n,\lambda,\mu}^{-1}$$

where

$$D_{n,\lambda,\mu} = \text{diag}(1, \tau, \tau^2, \dots, \tau^{n-1}), \quad \tau = \sqrt{\frac{\lambda}{\mu}},$$

$$X_{n,\lambda,\mu} = \begin{bmatrix} -\lambda & \sqrt{\lambda\mu} & & & \\ \sqrt{\lambda\mu} & -\lambda - \mu & \sqrt{\lambda\mu} & & \\ & \ddots & \ddots & \ddots & \\ & & \sqrt{\lambda\mu} & -\lambda - \mu & \sqrt{\lambda\mu} \\ & & & \sqrt{\lambda\mu} & -\mu \end{bmatrix}.$$

A direct verification shows that

$$X_{n,\lambda,\mu} = (-\lambda - \mu)I_n + \sqrt{\lambda\mu} T_{n,\varepsilon,\varphi} \quad \text{with} \quad \begin{cases} \varepsilon = \tau^{-1} = \sqrt{\frac{\mu}{\lambda}}, \\ \varphi = \tau = \sqrt{\frac{\lambda}{\mu}}. \end{cases}$$

Since $\varepsilon\varphi = 1$, the eigendecomposition of $X_{n,\lambda,\mu}$ (and hence also of $Q_{n,\lambda,\mu}^\top$) is immediately obtained from the results in Section 5.2. In particular, the eigenpairs of $Q_{n,\lambda,\mu}^\top$ are given by (ν_k, \mathbf{w}_k) , $k = 0, \dots, n - 1$, where

$$\nu_0 = 0, \quad \mathbf{w}_0 = [1, \tau^2, \tau^4, \dots, \tau^{2n-2}]^\top, \tag{6.2}$$

and, for $k = 1, \dots, n - 1$,

$$\begin{aligned} \nu_k &= -\lambda - \mu + 2\sqrt{\lambda\mu} \cos \theta_k, & \mathbf{w}_k &= [\tau^{i-1} \sin(i\theta_k) - \tau^{i-2} \sin((i-1)\theta_k)]_{i=1}^n, \\ \theta_k &= \frac{k\pi}{n}. \end{aligned} \tag{6.3}$$

Remark 6.1 (Steady-State Distribution). Since

$$\|\mathbf{w}_0\|_1 = \sum_{i=0}^{n-1} \tau^{2i} = \frac{1 - \tau^{2n}}{1 - \tau^2} = \frac{1 - \rho^n}{1 - \rho}, \quad \rho = \tau^2,$$

the steady-state (or stationary/limiting) distribution of the considered queuing model, i.e., the normalized positive eigenvector of $Q_{n,\lambda,\mu}^\top$ associated with the eigenvalue 0, is given by

$$\frac{\mathbf{w}_0}{\|\mathbf{w}_0\|_1} = \frac{1 - \rho}{1 - \rho^n} [1, \rho, \rho^2, \dots, \rho^{n-1}]^\top,$$

where it is understood that in the case $\rho = 1$ we take the limit $\rho \rightarrow 1$. For a different derivation, see [22, Section 5.7].

Remark 6.2 (Second Eigenvalue). It is clear from (6.3) and the inequality $\sqrt{\lambda\mu} \leq \frac{1}{2}(\lambda + \mu)$ that all nonzero eigenvalues of $Q_{n,\lambda,\mu}^\top$ are negative. The largest of them is $\nu_1 = -\lambda - \mu + 2\sqrt{\lambda\mu} \cos \frac{\pi}{n}$. This second eigenvalue gives information about the convergence speed to the

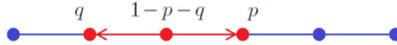


Fig. 6.1. Random walk in a unidimensional lattice.

steady-state distribution of power methods [8, p. 371]; see also [18] and [25, Section 7.2]. We will return to the second eigenvalue in Section 6.5.

Remark 6.3. The eigendecomposition of $Q_{n,\lambda,\mu}^\top$ is given by (6.2)–(6.3) for all $\lambda, \mu \in \mathbb{R}$ such that $\lambda\mu > 0$. Indeed, the above derivation requires only the hypothesis $\lambda\mu > 0$.

6.2. Random walk in a unidimensional lattice

Consider a discrete-time Markov chain with n states $1, \dots, n$ and with matrix of transition probabilities given by

$$P_{n,p,q} = \begin{bmatrix} 1-p & p & & & \\ q & 1-p-q & p & & \\ & \ddots & \ddots & \ddots & \\ & & q & 1-p-q & p \\ & & & q & 1-q \end{bmatrix}, \tag{6.4}$$

where $p, q > 0$ and $p + q \leq 1$. Markov chains of this kind are referred to as random walks in the unidimensional lattice $1, \dots, n$; see Fig. 6.1. The difference with respect to traditional random walks in \mathbb{Z} is that states 1 and n act as absorbing/reflecting barriers: when the system is in state 1, it cannot go to a hypothetical previous state 0 with probability q (as it happens for all other states), because the probability q of going to a previous state 0 is absorbed in the probability of staying in state 1, which grows from $1 - p - q$ to $1 - p$; a similar discussion applies to state n . In this section, we derive the eigendecomposition of $P_{n,p,q}^\top$ by simply noting that $P_{n,p,q}^\top = I_n + Q_{n,p,q}^\top$, where $Q_{n,p,q}$ is given by (6.1) for $(\lambda, \mu) = (p, q)$. By (6.2)–(6.3), the eigenpairs of $P_{n,p,q}^\top$ are given by (μ_k, \mathbf{w}_k) , $k = 0, \dots, n - 1$, where

$$\mu_0 = 1, \quad \mathbf{w}_0 = [1, \alpha^2, \alpha^4, \dots, \alpha^{2n-2}]^\top, \tag{6.5}$$

and, for $k = 1, \dots, n - 1$,

$$\begin{aligned} \mu_k &= 1 - p - q + 2\sqrt{pq} \cos \theta_k, & \mathbf{w}_k &= [\alpha^{i-1} \sin(i\theta_k) - \alpha^{i-2} \sin((i-1)\theta_k)]_{i=1}^n, \\ \theta_k &= \frac{k\pi}{n}, \end{aligned} \tag{6.6}$$

with $\alpha = \sqrt{p/q}$. The steady-state distribution of the unidimensional random walk, i.e., the normalized positive eigenvector of $P_{n,p,q}^\top$ associated with the eigenvalue 1, is given by

$$\frac{\mathbf{w}_0}{\|\mathbf{w}_0\|_1} = \frac{1 - \beta}{1 - \beta^n} [1, \beta, \beta^2, \dots, \beta^{n-1}]^\top, \quad \beta = \alpha^2,$$

where it is understood that in the case $\beta = 1$ we take the limit $\beta \rightarrow 1$.

6.3. Random walk in a multidimensional lattice

Let $\mathbf{n} = (n_1, \dots, n_d) \in \mathbb{N}^d$ and let $\mathbf{1}, \dots, \mathbf{n}$ be the multi-index range $\{\mathbf{i} \in \mathbb{N}^d : 1 \leq \mathbf{i} \leq \mathbf{n}\}$, where $\mathbf{1} = (1, \dots, 1)$ and inequalities between vectors must be interpreted componentwise. When writing $\mathbf{i} = \mathbf{1}, \dots, \mathbf{n}$, we mean that \mathbf{i} varies in $\mathbf{1}, \dots, \mathbf{n}$ following the lexicographic ordering: $[\dots [(i_1, \dots, i_d)]_{i_d=1, \dots, n_d}]_{i_{d-1}=1, \dots, n_{d-1}} \dots]_{i_1=1, \dots, n_1}$; see [21, Section 2.1.2] for more details on the multi-index notation.

Consider a discrete-time Markov chain with $\prod_{i=1}^d n_i$ states $\mathbf{1}, \dots, \mathbf{n}$ and with matrix of transition probabilities

$$P_{\mathbf{n}, \mathbf{p}, \mathbf{q}} = \bigotimes_{r=1}^d P_{n_r, p_r, q_r},$$

where

- $\mathbf{p} = (p_1, \dots, p_d)$ and $\mathbf{q} = (q_1, \dots, q_d)$ satisfy $\mathbf{p}, \mathbf{q} > \mathbf{0}$ and $\mathbf{p} + \mathbf{q} \leq \mathbf{1}$,
- the matrix P_{n_r, p_r, q_r} is defined by (6.4) for $(n, p, q) = (n_r, p_r, q_r)$,
- \bigotimes denotes the tensor (Kronecker) product.

Markov chains of this kind are referred to as random walks in the d -dimensional lattice $\mathbf{1}, \dots, \mathbf{n}$. They are a generalization of the unidimensional random walks discussed in Section 6.2. By the properties of tensor products [21, Section 2.5], for all $\mathbf{i}, \mathbf{j} = \mathbf{1}, \dots, \mathbf{n}$, the probability of going from state \mathbf{i} to state \mathbf{j} is given by $(P_{\mathbf{n}, \mathbf{p}, \mathbf{q}})_{\mathbf{i}\mathbf{j}} = \prod_{r=1}^d (P_{n_r, p_r, q_r})_{i_r j_r}$, and it is equal to the product for $r = 1, \dots, d$ of the probability of going from state i_r to state j_r in a unidimensional random walk with transition matrix P_{n_r, p_r, q_r} as considered in Section 6.2. In short, a d -dimensional random walk is the result of d independent unidimensional random walks (one for each space dimension); see Fig. 6.2 for a bidimensional illustration. By the properties of tensor products and the results of Section 6.2, we immediately obtain the eigendecomposition of $P_{\mathbf{n}, \mathbf{p}, \mathbf{q}}^\top$: the eigenpairs of $P_{\mathbf{n}, \mathbf{p}, \mathbf{q}}^\top$ are given by $(\mu_{\mathbf{k}}, \mathbf{w}_{\mathbf{k}})$, $\mathbf{k} = \mathbf{0}, \dots, \mathbf{n} - \mathbf{1}$, where

$$\mu_{\mathbf{k}} = \prod_{r=1}^d \mu_{k_r}, \quad \mathbf{w}_{\mathbf{k}} = \bigotimes_{r=1}^d \mathbf{w}_{k_r},$$

and $(\mu_{k_r}, \mathbf{w}_{k_r})$ is defined by (6.5)–(6.6) for $(k, n, p, q, \alpha) = (k_r, n_r, p_r, q_r, \alpha_r)$ with $\alpha_r = \sqrt{p_r/q_r}$. The steady-state distribution of the d -dimensional random walk is given by

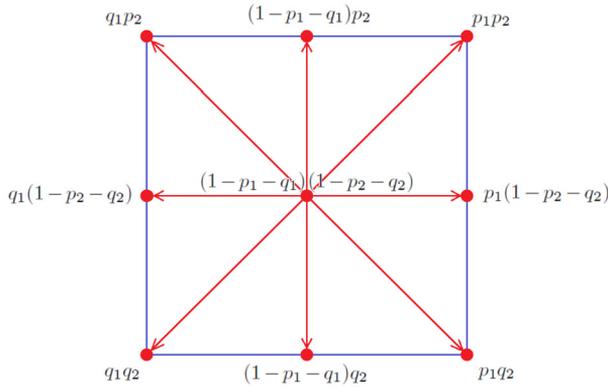


Fig. 6.2. Random walk in a bidimensional lattice.

$$\frac{\mathbf{w}_0}{\|\mathbf{w}_0\|_1} = \bigotimes_{r=1}^d \frac{1 - \beta_r}{1 - \beta_r^{n_r}} [1, \beta_r, \beta_r^2, \dots, \beta_r^{n_r-1}]^\top, \quad \beta_r = \alpha_r^2,$$

i.e., it is the tensor product of the steady-state distributions of the unidimensional random walks that compose it.

6.4. Multidimensional diffusion processes

Consider a d -dimensional diffusion process, where the diffusions in each dimension are independent of each other and subject to a reflecting boundary condition at each side. We assume that, for every $r = 1, \dots, d$, the direction x_r is discretized uniformly with n_r nodes separated by a discretization step $\Delta_r > 0$. This discretization gives rise to a $n_1 \times \dots \times n_d$ lattice whose points \mathbf{x}_i are naturally indexed by a multi-index $\mathbf{i} = 1, \dots, \mathbf{n}$, with $\mathbf{n} = (n_1, \dots, n_d)$. The diffusion in direction x_r is a Brownian motion characterized by two parameters: a drift $\mu_r \in \mathbb{R}$ and a variance $\sigma_r^2 > 0$. For the direction x_r , the infinitesimal generator L_{n_r, μ_r, σ_r} coincides with the generator of a 1-dimensional diffusion process with drift μ_r and variance σ_r^2 discretized uniformly with n_r nodes separated by a discretization step Δ_r . In formulas,

$$L_{n_r, \mu_r, \sigma_r} = Q_{n_r, \tilde{\lambda}_r, \tilde{\mu}_r}, \quad \tilde{\lambda}_r = \begin{cases} \frac{\sigma_r^2}{2\Delta_r^2}, & \text{if } \mu_r \leq 0, \\ \frac{\sigma_r^2}{2\Delta_r^2} + \frac{\mu_r}{\Delta_r}, & \text{if } \mu_r \geq 0, \end{cases}$$

$$\tilde{\mu}_r = \begin{cases} \frac{\sigma_r^2}{2\Delta_r^2} - \frac{\mu_r}{\Delta_r}, & \text{if } \mu_r \leq 0, \\ \frac{\sigma_r^2}{2\Delta_r^2}, & \text{if } \mu_r \geq 0, \end{cases}$$

where $Q_{n,\lambda,\mu}$ is defined in (6.1). The differential operator (infinitesimal generator) of the d -dimensional diffusion process is given by

$$L_{\mathbf{n},\boldsymbol{\mu},\boldsymbol{\sigma}} = \sum_{i=1}^d I_{n_1} \otimes \cdots \otimes I_{n_{i-1}} \otimes L_{n_r,\mu_r,\sigma_r} \otimes I_{n_{i+1}} \otimes \cdots \otimes I_{n_d}, \tag{6.7}$$

where $\boldsymbol{\mu} = (\mu_1, \dots, \mu_d)$ and $\boldsymbol{\sigma} = (\sigma_1, \dots, \sigma_d)$. More details on the discretized multidimensional diffusion process considered here will be given in Section 6.5 along with an economics application; for more on diffusion processes, see [3] for a mathematical treatment and [1,2,18] for an economical application-oriented approach. By the properties of tensor products and the results of Section 6.1, we can immediately obtain the eigen-decomposition of $L_{\mathbf{n},\boldsymbol{\mu},\boldsymbol{\sigma}}^\top$. In particular, the eigenpairs of $L_{\mathbf{n},\boldsymbol{\mu},\boldsymbol{\sigma}}^\top$ are given by $(\nu_{\mathbf{k}}, \mathbf{w}_{\mathbf{k}})$, $\mathbf{k} = \mathbf{0}, \dots, \mathbf{n} - \mathbf{1}$, where

$$\nu_{\mathbf{k}} = \sum_{r=1}^d \nu_{k_r}, \quad \mathbf{w}_{\mathbf{k}} = \bigotimes_{r=1}^d \mathbf{w}_{k_r},$$

and $(\nu_{k_r}, \mathbf{w}_{k_r})$ is defined by (6.2)–(6.3) for $(k, n, \lambda, \mu, \tau) = (k_r, n_r, \tilde{\lambda}_r, \tilde{\mu}_r, \tilde{\tau}_r)$ with $\tilde{\tau}_r = \sqrt{\tilde{\lambda}_r/\tilde{\mu}_r}$. The steady-state distribution of the d -dimensional diffusion process generated by $L_{\mathbf{n},\boldsymbol{\mu},\boldsymbol{\sigma}}$, i.e., the normalized positive eigenvector of $L_{\mathbf{n},\boldsymbol{\mu},\boldsymbol{\sigma}}^\top$ associated with the eigenvalue 0, is given by

$$\mathbf{p} = \frac{\mathbf{w}_0}{\|\mathbf{w}_0\|_1} = \bigotimes_{r=1}^d \frac{1 - \tilde{\rho}_r}{1 - \tilde{\rho}_r^{n_r}} [1, \tilde{\rho}_r, \tilde{\rho}_r^2, \dots, \tilde{\rho}_r^{n_r-1}]^\top = \bigotimes_{r=1}^d \mathbf{p}_r, \quad \tilde{\rho}_r = \tilde{\tau}_r^2, \tag{6.8}$$

i.e., it is the tensor product of the steady-state distributions \mathbf{p}_r of the unidimensional diffusion processes generated by the operators L_{n_r,μ_r,σ_r} , $r = 1, \dots, d$.

6.5. Dynamics of wealth and income inequality

In this section, we present an economic application of the results obtained in Section 6.4. We begin with an overview of the topic, which may not be so familiar to non-economists.

6.5.1. Modeling the evolution of wealth and income

The sources of the vast wealth and income inequality is a key topic of study within macroeconomics and finance [1,2,4,5]. Central to the questions of inequality are: What is the source of heterogeneity that drives the stationary distribution of income or wealth? How would the income or wealth distribution evolve over time given aggregate changes? For example, researchers can ask how the stationary distribution of wealth will change—and how long it will take to be reached—given experiments such as a new income tax or

increases in the returns on an asset such as housing. The analysis of income inequality is done by examining the stationary distribution of discrete- or continuous-time stochastic processes associated with income or wealth. Typically, researchers act as follows.

- They choose a stochastic process for the assets of interest (for example, housing wealth, human wealth (i.e., wages), stocks, bonds, social security income, etc.).
- They use data to estimate the parameters of the stochastic process for that “portfolio” of assets. In some cases, the parameters are derived from optimal control of a Hamilton–Jacobi–Bellman equation [1,2,5].
- They solve for the stationary distribution associated with the stochastic process. In this way, they can examine properties of the distribution, relate it back to the data, and conduct hypotheticals on the impact of policy.

With this approach, the emphasis on the steady-state distribution has come out of necessity. Even the convergence speed to the steady state has recently become an active research field [19,27].

6.5.2. Continuous-state formulation

Consider a portfolio of d assets $\mathbf{X}(t) = (X_1(t), \dots, X_d(t))$ evolving over time. We assume that $X_1(t), \dots, X_d(t)$ are d independent Brownian motions with drifts μ_1, \dots, μ_d and variances $\sigma_1^2, \dots, \sigma_d^2$. We also assume that $X_1(t), \dots, X_d(t)$ take values in $[0, 1]$, so that the portfolio $\mathbf{X}(t)$ determining an individual’s wealth is an element $\mathbf{x} = (x_1, \dots, x_d) \in [0, 1]^d$ at any time t . The resulting stochastic process $\mathbf{X}(t)$ is a d -dimensional Brownian motion with drifts $\boldsymbol{\mu} = (\mu_1, \dots, \mu_d)$ and variances $\boldsymbol{\sigma}^2 = (\sigma_1^2, \dots, \sigma_d^2)$, and with the edges of $[0, 1]^d$ acting as reflecting barriers. The probability density function $p_r(x_r, t)$ for the asset $X_r(t)$ at time t is determined by the Kolmogorov forward (Fokker–Planck) equation

$$\frac{\partial p_r}{\partial t}(x_r, t) = -\mu_r \frac{\partial p_r}{\partial x_r}(x_r, t) + \frac{\sigma_r^2}{2} \frac{\partial^2 p_r}{\partial x_r^2}(x_r, t) \tag{6.9}$$

subject to the boundary conditions induced by reflecting boundaries at 0 and 1:

$$0 = -\mu_r p_r(x_r, t) + \frac{\sigma_r^2}{2} \frac{\partial p_r}{\partial x_r}(x_r, t), \quad x_r = 0, 1. \tag{6.10}$$

The objects of interest are the following.

- The stationary density function $p_r(x_r)$, i.e., the density function independent of t satisfying (6.9)–(6.10). The function $p_r(x_r)$ does not evolve over time and determines the limiting (equilibrium) density function $p(\mathbf{x}) = p_1(x_1) \cdots p_d(x_d)$ characterizing the steady-state probability distribution of the process.

- Any function W that maps a state $\mathbf{x} \in [0, 1]^d$ to a scalar “wealth” or “payoff” $W(\mathbf{x})$.¹ Clearly, $W(\mathbf{X}(t))$ is a random variable evolving over time together with the portfolio $\mathbf{X}(t)$, and we are interested in quantities like the average wealth $\mathbb{E}[W(\mathbf{X})]$ and the wealth variance $\text{Var}[W(\mathbf{X})]$ computed in the steady-state distribution $p(\mathbf{x})$, i.e.,

$$\begin{aligned} \mathbb{E}[W(\mathbf{X})] &= \int_{[0,1]^d} W(\mathbf{x})p(\mathbf{x})d\mathbf{x}, \\ \text{Var}[W(\mathbf{X})] &= \mathbb{E}[W(\mathbf{X})^2] - \mathbb{E}[W(\mathbf{X})]^2 \\ &= \int_{[0,1]^d} W(\mathbf{x})^2p(\mathbf{x})d\mathbf{x} - \left(\int_{[0,1]^d} W(\mathbf{x})p(\mathbf{x})d\mathbf{x} \right)^2. \end{aligned}$$

6.5.3. Discrete-state formulation

Suppose we discretize $[0, 1]^d$ by introducing a $n_1 \times \dots \times n_d$ lattice with n_r points in direction x_r separated by a discretization step $\Delta_r > 0$, as in Section 6.4. This essentially means that we allow each asset $X_r(t)$ to assume only a finite number of values. Consequently, the portfolio $\mathbf{X}(t)$ can only be in a finite number of states $\mathbf{x}_1, \dots, \mathbf{x}_n \in [0, 1]^d$. The use of upwind finite differences allow us to convert the $2d$ PDEs (6.9)–(6.10) to a unique system of ODEs

$$\frac{d\mathbf{p}}{dt}(t) = L_{\mathbf{n},\boldsymbol{\mu},\boldsymbol{\sigma}}^\top \mathbf{p}(t) \tag{6.11}$$

subject to an initial condition $\mathbf{p}(0)$, where $L_{\mathbf{n},\boldsymbol{\mu},\boldsymbol{\sigma}}$ is the infinitesimal generator (6.7) and $\mathbf{p}_i(t)$ is the probability that the portfolio $\mathbf{X}(t)$ is in state \mathbf{x}_i at time t . After this discretization, the continuous-state continuous-time Markov process of Section 6.5.2 is changed into a discrete-state continuous-time Markov chain. Here, the objects of interest are the discrete counterparts of those mentioned in Section 6.5.2, i.e., the following.

- The stationary distribution $\mathbf{p} = (p_1, \dots, p_n)$ of the process, i.e., the probability vector independent of t satisfying (6.11). Clearly, \mathbf{p} is given by (6.8).
- Any function W that maps a state \mathbf{x}_i to a scalar “wealth” or “payoff” $W(\mathbf{x}_i) = W_i$. Clearly, $W(\mathbf{X}(t))$ is a random variable evolving over time together with the portfolio $\mathbf{X}(t)$, and we are interested in quantities like the average wealth $\mathbb{E}[W(\mathbf{X})]$ and the wealth variance $\text{Var}[W(\mathbf{X})]$ computed in the steady-state distribution \mathbf{p} , i.e.,

$$\mathbb{E}[W(\mathbf{X})] = \mathbf{W} \cdot \mathbf{p}, \tag{6.12}$$

$$\text{Var}[W(\mathbf{X})] = \mathbb{E}[W(\mathbf{X})^2] - \mathbb{E}[W(\mathbf{X})]^2 = \mathbf{W}^2 \cdot \mathbf{p} - (\mathbf{W} \cdot \mathbf{p})^2, \tag{6.13}$$

¹ As an example in the case $d = 2$, asset $X_1(t)$ could be housing wealth at time t and asset $X_2(t)$ could be bank holdings at time t in an individual’s portfolio. If w_1 is the per-unit value of a house and w_2 the per-unit value of a bank holding, then the “wealth” of an individual in state $(X_1, X_2) = (x_1, x_2)$ is $W(x_1, x_2) = w_1x_1 + w_2x_2$.

where $\mathbf{W} = (W_1, \dots, W_n)$ is the vector (tensor) of payoffs and \mathbf{W}^2 is the componentwise square of \mathbf{W} (in general, operations on vectors that have no meaning in themselves must be interpreted in the componentwise sense).

Since \mathbf{p} is known, formulas (6.12)–(6.13) allow us to compute the average wealth and the wealth variance in the steady state of the process. This lets us analyze different hypothetical scenarios. For example, one could analyze how the wealth variance (a simple measure of inequality) would change if the variance of wages increases.

6.5.4. Convergence speed to the steady state

The results of Section 6.4 allow us to quantify the convergence speed to the steady state of the Markov chain presented in Section 6.5.3. Indeed, as we know from Section 6.4, all nonzero eigenvalues of $L_{\mathbf{n}, \boldsymbol{\mu}, \boldsymbol{\sigma}}$ are negative and the largest of them, i.e., the second largest eigenvalue after 0, is given by

$$\nu = \max_{r=1, \dots, d} \left(-\tilde{\lambda}_r - \tilde{\mu}_r + 2\sqrt{\tilde{\lambda}_r \tilde{\mu}_r \cos \frac{\pi}{n_r}} \right).$$

The second eigenvalue provides a measure of the convergence speed to the steady state because, for essentially every choice of the initial distribution $\mathbf{p}(0)$, the quantities $\mathbf{p}(t)$, $\mathbb{E}[W(\mathbf{X}(t))]$, $\text{Var}[W(\mathbf{X}(t))]$ converge to their stationary counterparts \mathbf{p} , $\mathbb{E}[W(\mathbf{X})]$, $\text{Var}[W(\mathbf{X})]$ in (6.8), (6.12), (6.13) with asymptotic convergence rates given by

$$\begin{aligned} \lim_{t \rightarrow \infty} \frac{d}{dt} \ln \|\mathbf{p}(t) - \mathbf{p}\|_2 &= \lim_{t \rightarrow \infty} \frac{d}{dt} \ln |\mathbb{E}[W(\mathbf{X}(t))] - \mathbb{E}[W(\mathbf{X})]| \\ &= \lim_{t \rightarrow \infty} \frac{d}{dt} \ln |\text{Var}[W(\mathbf{X}(t))] - \text{Var}[W(\mathbf{X})]| = \nu; \end{aligned}$$

see [18] and [25, Section 7.2] for more details.

6.5.5. Derivatives with respect to drifts and variances

For the convenience of economists, we here report the derivatives of the steady-state distribution \mathbf{p} in (6.8), the average wealth $\mathbb{E}[W(\mathbf{X})]$ in (6.12), and the wealth variance $\text{Var}[W(\mathbf{X})]$ in (6.13) with respect to the drifts $\boldsymbol{\mu}$ and the variances $\boldsymbol{\sigma}^2$. For $r = 1, \dots, d$, we have

$$\begin{aligned} \frac{\partial \tilde{\rho}_r}{\partial \mu_r} &= \begin{cases} \frac{\sigma_r^2}{2\Delta_r^3 \tilde{\mu}_r^2} = \frac{2\Delta_r \sigma_r^2}{(\sigma_r^2 - 2\Delta_r \mu_r)^2}, & \text{if } \mu_r \leq 0, \\ \frac{1}{\Delta_r \tilde{\mu}_r} = \frac{2\Delta_r}{\sigma_r^2}, & \text{if } \mu_r \geq 0, \end{cases} \\ \frac{\partial \tilde{\rho}_r}{\partial \sigma_r^2} &= -\frac{\mu_r}{2\Delta_r^3 \tilde{\mu}_r^2}, \end{aligned}$$

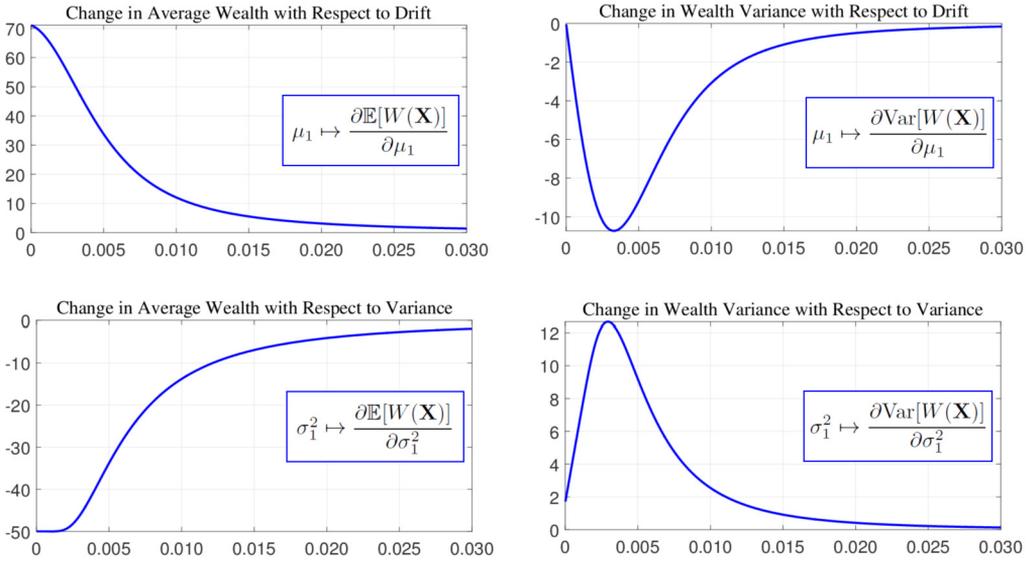


Fig. 6.3. Changes in moments of the wealth distribution. Parameters are chosen to be illustrative: $\mu_1 = \mu_2 = 0.01$, $\sigma_1^2 = \sigma_2^2 = 0.0025$, and $W(x_1, x_2) = x_1 + x_2$.

$$\begin{aligned} \frac{\partial \mathbf{p}_r}{\partial \tilde{\rho}_r} &= \frac{(1 - n_r)\tilde{\rho}_r^{n_r} + n_r\tilde{\rho}_r^{n_r-1} - 1}{(1 - \tilde{\rho}_r^{n_r})^2} [1, \tilde{\rho}_r, \tilde{\rho}_r^2, \dots, \tilde{\rho}_r^{n_r-1}]^\top \\ &\quad + \frac{1 - \tilde{\rho}_r}{1 - \tilde{\rho}_r^{n_r}} [0, 1, 2\tilde{\rho}_r, \dots, (n_r - 1)\tilde{\rho}_r^{n_r-2}]^\top, \end{aligned}$$

$$\frac{\partial \mathbf{p}_r}{\partial \mu_r} = \frac{\partial \tilde{\rho}_r}{\partial \mu_r} \frac{\partial \mathbf{p}_r}{\partial \tilde{\rho}_r},$$

$$\frac{\partial \mathbf{p}_r}{\partial \sigma_r^2} = \frac{\partial \tilde{\rho}_r}{\partial \sigma_r^2} \frac{\partial \mathbf{p}_r}{\partial \tilde{\rho}_r},$$

$$\frac{\partial \mathbf{p}}{\partial \mu_r} = \mathbf{p}_1 \otimes \dots \otimes \mathbf{p}_{r-1} \otimes \frac{\partial \mathbf{p}_r}{\partial \mu_r} \otimes \mathbf{p}_{r+1} \otimes \dots \otimes \mathbf{p}_d, \tag{6.14}$$

$$\frac{\partial \mathbf{p}}{\partial \sigma_r^2} = \mathbf{p}_1 \otimes \dots \otimes \mathbf{p}_{r-1} \otimes \frac{\partial \mathbf{p}_r}{\partial \sigma_r^2} \otimes \mathbf{p}_{r+1} \otimes \dots \otimes \mathbf{p}_d, \tag{6.15}$$

$$\frac{\partial \mathbb{E}[W(\mathbf{X})]}{\partial \mu_r} = \mathbf{W} \cdot \frac{\partial \mathbf{p}}{\partial \mu_r}, \tag{6.16}$$

$$\frac{\partial \mathbb{E}[W(\mathbf{X})]}{\partial \sigma_r^2} = \mathbf{W} \cdot \frac{\partial \mathbf{p}}{\partial \sigma_r^2}, \tag{6.17}$$

$$\frac{\partial \text{Var}[W(\mathbf{X})]}{\partial \mu_r} = \mathbf{W}^2 \cdot \frac{\partial \mathbf{p}}{\partial \mu_r} - 2(\mathbf{W} \cdot \mathbf{p}) \left(\mathbf{W} \cdot \frac{\partial \mathbf{p}}{\partial \mu_r} \right), \tag{6.18}$$

$$\frac{\partial \text{Var}[W(\mathbf{X})]}{\partial \sigma_r^2} = \mathbf{W}^2 \cdot \frac{\partial \mathbf{p}}{\partial \sigma_r^2} - 2(\mathbf{W} \cdot \mathbf{p}) \left(\mathbf{W} \cdot \frac{\partial \mathbf{p}}{\partial \sigma_r^2} \right). \tag{6.19}$$

We remark that the above derivatives are defined even in the case $\mu_r = 0$ and their values in this case are obtained by taking the limit of the corresponding expression as $\mu_r \rightarrow 0$. The derivatives (6.14)–(6.15) enable an analysis of how the steady state changes when properties of the underlying process change. For example, if the volatility of housing prices σ_1^2 increases, equations (6.14)–(6.15) provide the resulting impact on the steady state. The derivatives (6.16)–(6.19) can be used to examine how key moments of the stationary distribution change. For example, a researcher could analyze the impact on the steady-state variance of the wealth distribution, i.e., $\text{Var}[W(\mathbf{X})]$, in the case where the volatility of housing prices σ_1^2 increases. Fig. 6.3 illustrates this by showing how the mean and variance of the stationary wealth distribution change with respect to the parameters of the underlying stochastic process. The figure has been realized through a discretization of the square $[0, 1]^2$ by a $n_1 \times n_2$ lattice with $n_1 = n_2 = 31$ points in each direction and (consequently) two equal discretization steps $\Delta_1 = \Delta_2 = 1/30$. It should be noted, however, that the graphs in Fig. 6.3 do not really depend on n_1 and n_2 , because they converge to limiting graphs as $n_1, n_2 \rightarrow \infty$ (and convergence is already reached for $n_1 = n_2 = 31$).

7. Conclusions and perspectives

We have studied the spectral properties of the generator $T_{n,\varepsilon,\varphi}$ of the $\tau_{\varepsilon,\varphi}$ algebra introduced by Bozzo and Di Fiore in the context of matrix displacement decomposition [10]. In particular:

- we have derived precise asymptotics for the outliers of $T_{n,\varepsilon,\varphi}$ and the associated eigenvectors;
- through a different approach with respect to Losonczy [26], we have obtained the equations for the eigenvalues and eigenvectors of $T_{n,\varepsilon,\varphi}$, with a focus on the hyperbolic equations for the outlier eigenpairs;
- we have computed the full eigendecomposition of $T_{n,\varepsilon,\varphi}$ in the case $\varepsilon\varphi = 1$.

Finally, we have presented applications of our results to queuing models, random walks, diffusion processes, and economics, with a special emphasis on wealth/income inequality and portfolio dynamics. We conclude this paper by mentioning a few possible future lines of research.

1. The applications presented herein do not exhaust all possible applications of the $\tau_{\varepsilon,\varphi}$ algebra. For example, $\tau_{\varepsilon,\varphi}$ matrices arise in the discretization of differential equations by finite difference methods, finite element methods and, as recently discovered, iso-geometric methods [17, Section 3]. A future research could take care of investigating further discretizations where $\tau_{\varepsilon,\varphi}$ matrices arise and, consequently, the results of this paper apply.

2. On the economics side, Sections 6.4–6.5 are interesting and useful, but the reflected constant-coefficient diffusion process $\mathbf{X}(t)$ that has been considered therein is not sufficient to understand top income inequality, since in that case researchers need alternative specifications [4,19]. That said, there could be a large class of stochastic processes $\hat{\mathbf{X}}(t)$ that can be mapped to $\mathbf{X}(t)$ through an appropriate change of measure. Loosely, given a stochastic process $\hat{\mathbf{X}}(t)$, let \hat{W} be a mapping such that $\hat{W}(\hat{\mathbf{X}}(t))$ represents the “wealth” of an individual with portfolio $\hat{\mathbf{X}}(t)$. Then, there may exist a change of measure $\mathbb{P} \rightarrow \mathbb{Q}$ (i.e., a Radon–Nikodym derivative $d\mathbb{Q}/d\mathbb{P}$) mapping $\hat{\mathbf{X}}(t)$ to $\mathbf{X}(t)$ and $\hat{W}(\hat{\mathbf{X}}(t))$ to $W(\mathbf{X}(t))$ for a suitable W . If so, then the computation of, say, the average wealth $\mathbb{E}_{\mathbb{P}}[\hat{W}(\hat{\mathbf{X}})]$ in the steady-state distribution of process $\hat{\mathbf{X}}(t)$ could be traced back to computing the corresponding expectation $\mathbb{E}_{\mathbb{Q}}[W(\mathbf{X})]$ for process $\mathbf{X}(t)$ as we have done in Section 6.5; see [11, Section 9.5] for an analysis of changes in probability measures and associated expectations, as well as for practical tools for working with such concepts. A careful investigation of all this topic may form the content of a future research that would extend the applicability of the results presented in this paper.

Declaration of competing interest

The authors declare that they have no competing interest.

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